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Vorrichtung zur Programmfehlerbeseitigung

Système de débogage d'un programme

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EP-A- 0 588 473 **WO-A-92/15962**
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• **ROBERT D. GRONLUND ET AL.:** "The HP 64700
Embedded Debug Environment: A New
Paradigm for Embedded System Integration and
Debugging" **HEWLETT-PACKARD JOURNAL**,
vol. 44, no. 2, April 1993, PALO ALTO US, pages
90-106, XP000360990

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Description**BACKGROUND OF THE INVENTION****(1) Field of the Invention**

[0001] This invention relates to a debugging apparatus, and more specifically, to a debugging apparatus for debugging a debug target program by changing hardware environments without changing program operation state.

(2) Description of the Prior Art

[0002] Microcomputer systems are indispensable to electrical appliances today. In developing programs for such microcomputer systems, debugging is very important since microcomputer systems require such a quality as enduring mass production.

[0003] For debugging programs, the debug target programs are run in hardware environments to find errors (bugs). The bugs found are deleted from the programs.

[0004] The hardware environments in which debug target programs run are classified as follows:

- (1) target machine prototypes;
- (2) evaluation boards; and
- (3) simulators on host computers.

[0005] The hardware environment of (1) above is called "monitor type." In the monitor type hardware environment, operations of prototype microprocessors are monitored and simple debugging is performed.

[0006] The hardware environment of (2) above enables a high-quality debugging, using an in-circuit emulators (ICE) and various debugging tools. This hardware environment is called "ICE type."

[0007] The hardware environment of (3) above is called "simulator type." The simulators used in the environment are divided into two types: instruction level software simulators and logic level software simulators. Instruction level software simulators are such software systems as realizing, in a host computer, pseudo operation states of microprocessors by executing instructions of the microprocessors in the host computer.

[0008] The logic level software simulators simulate hardware operations and are generally used for designing microprocessor chips.

[0009] Meanwhile, these three types of hardware environments have their limitations respectively in the ability of testing operations.

[0010] In the ICE type hardware environment, the trace function can be used to output history of program operations. In the monitor type hardware environment, in contrast, it is difficult to use the trace function since it requires a great amount of memory capacity. Therefore, the operator is obliged to analyze the cause of bugs with

other less-quality functions in the monitor type. It may be said that the program verification in the monitor type is insufficient since various cases such as multiple interrupts, interrupts at an appointed time, etc cannot be applied to the debug target program. On the other hand, modifying the hardware monitor machine is not realistic.

[0011] The limitations of the ICE type hardware environment derive from the difference in the circuit structure between the evaluation board and the target microprocessor. Even if the microprocessor appears to operate perfectly on the evaluation board, it is not enough to permit the shipping of the microprocessor. The microprocessor should be verified with its peripherals. Lines in the evaluation board, for example, may be longer than those of a prototype microprocessor. This may generate a time lag when using the peripherals, which results in incorrectness of the microprocessor verification.

[0012] The limitation of the simulator type hardware environment derives from the slowness of operations. This is because the simulator itself uses the host computer. A process which takes one second in the ICE type or monitor type hardware environment, for example, takes several minutes or tens of several minutes in the simulator type hardware environment.

[0013] When an error occurs in a certain situation in a hardware environment, the operator may desire to reproduce the same situation in another hardware environment. Reproducing of such situations, however, generally requires a lot of trials and errors before the reproduction succeeds, such as transferring values at the time when an error occurred to the other environment, or running the debug target program from the beginning, etc. Such trials and errors takes a lot of time in the development of the microprocessor.

[0014] The document Robert D. Gronlund et al: "The HP 64700 Embedded Debug Environment: A New Paradigm for Embedded Systems Integration and Debugging", HEWLETT-PACKARD JOURNAL, vol. 44, No. 2, April 1993, Palo Alto, US, describes a debugging system for embedded systems using emulator systems for simulation and analysts purposes. Also simulator tools are described in the context of embedded system debugging.

SUMMARY OF THE INVENTION

[0015] It is therefore an object of the present invention to provide a debugging apparatus which makes the most of the advantage of each of different hardware environments by controlling the hardware environments.

[0016] It is another object of the present invention to provide a debugging apparatus for, when an error occurs in a certain situation in a hardware environment, reproducing the same situation in another hardware environment, without causing the developer to perform a lot of trials and errors.

[0017] The invention, as defined in claim 1, achieves the above objects by a debugging apparatus for verify-

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ing a program, which is to be embedded into a target machine, by running the program in any of the target machine itself, an emulator machine emulating the target machine, and a simulator simulating the target machine in terms of software, where each of the target machine, the emulator machine, and the simulator includes operation state information which indicates an operation state of the program and inputs and outputs the operation state information in a form unique to each of the target machine, the emulator machine, and the simulator, the debugging apparatus including: target environment storing unit for storing information of a target environment which is an identification name of any of the target machine, the emulator machine, and the simulator as an environment target; receiving unit for receiving a command input by an operator; instruction detecting unit for judging whether a certain instruction is included in the command received by the receiving unit; specifying unit for, when the instruction detecting unit judges that the certain instruction is included in the command, specifying a target environment specified by the identification name stored in the target environment storing unit as a source target environment and for specifying, as a destination target environment, one of the target machine, the emulator machine, and the simulator other than the identification name stored in the target environment storing unit; reading unit for reading operation state information from the source target environment; converting unit for converting the operation state information read by the reading unit into operation state information written in a form unique to the destination target environment; setting unit for setting the operation state information written in the form unique to the destination target environment in the destination target environment; and operation resuming unit for resuming an operation of the program in the destination target environment.

[0018] With such a construction, the debugging apparatus enables the operator to switch the hardware environments in debugging the debug target program. That means the operator can effectively debug the debug target program, making the most of the advantage of each of different hardware environments.

[0019] The first part of a debug target program, for example, may be run in the prototype hardware environment. Then, the rest of the debug target program may be run in the simulator type hardware environment. This is because the simulator type takes a lot of time in running the program, though it has a lot of functions for analyzing the cause of bugs. This tactic is very effective when to find such a bug as occurring once in several tens or several hundreds of executions of the debug target program. This decreases the time of debugging.

[0020] Another advantageous aspect of the present invention is that the hardware environments are switched by an issue of a command, which is a handy method and may be possible in any situations in the execution of debugging. That means the operator can an-

alyze the cause of the bug without taking much time for the development.

[0021] The debug target program also need not be run from the beginning in another hardware environment to reproduce the same situation for an error, while in conventional systems, values are transferred to the other hardware environment and the program is repeated from the beginning. This also decreases the time of debugging, and accordingly the time of developing.

[0022] The above debugging apparatus may further include: breakpoint setting managing unit for managing areas of the memories and the registers of the target machine, the emulator machine, and the simulator by classifying the areas into areas for which a breakpoint can be set and areas for which a breakpoint cannot be set; judging unit for judging whether a breakpoint is to be set in the destination target environment by referring to the breakpoint setting managing unit after the converting unit has converted the operation state information into the form of the destination target environment; and notifying unit for notifying the operator that the breakpoint is not to be set in the destination target environment when the judging unit judges that the breakpoint is not to be set in the destination target environment.

[0023] With such a construction it is possible for the debugging apparatus to inform the operator that a part of breakpoints cannot be set in the destination target hardware environment.

[0024] The above debugging apparatus may further comprise: maximum value storing unit for storing a value representing the maximum number of accumulated addresses for each of the target machine, the emulator machine, and the simulator; address number recognizing unit for recognizing a current number of accumulated addresses in the destination target environment; and notifying unit for notifying the operator of a difference between the current number of accumulated addresses and the maximum number of accumulated addresses.

[0025] With such a construction, it is possible for the debugging apparatus to inform the operator that a part of trace data accumulated in the source target hardware environment is lost in the destination target hardware environment.

BRIEF DESCRIPTION OF THE DRAWINGS

[0026] These and other objects, advantages and features of the invention will become apparent from the following description thereof taken in conjunction with the accompanying drawings which illustrate a specific embodiment of the invention. In the drawings:

FIG.1A shows an appearance of the debugging apparatus of the present embodiment;

FIG.1B is a block diagram showing the hardware construction of the debugging apparatus of the present embodiment;

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FIG.2A shows the hardware construction of the monitor type hardware environment;

FIG.2B shows the hardware construction of the ICE type hardware environment;

FIG.2C shows the construction of the simulator type hardware environment;

FIG.3 shows internal layers of the debugging apparatus;

FIG.4 shows the sub-layers in application layer 11;

FIG.5 shows the contents of the sub-layers in application layer 11;

FIG.6A is a systematic illustration of debug commands which are used in the present embodiment;

FIG.6B shows three major examples of the extended selectTARGET commands;

FIG.6C shows a table which shows destination target hardware environments;

FIG.7 shows messages output onto display 2 by user interface layer 50;

FIG.8 shows the sub-commands and the corresponding function call codes;

FIG.9 shows the high function call codes and corresponding low function call codes;

FIG.10A shows the control of reading data from work area 38 in prototype 30 by monitor control layer 61;

FIG.10B shows the control of writing data into work area 38 in prototype 30 by monitor control layer 61;

FIG.11A is a flowchart of the procedure of the communications sequence to control reading data from memories, which is performed by monitor control layer 61;

FIG.11B is a flowchart of the procedure of the communications sequence to control writing of data into a memory, which is performed by monitor control layer 61;

FIG.12A shows the control of the data reading by ICE control layer 62;

FIG.12B shows the control by ICE control layer 62 when ICE control layer 62 writes data into debug target program 37 in evaluation board 20;

FIG.13A shows the transportation of state information when the selectTARGET command specifying the simulator type hardware environment as the destination target hardware environment is input while the program runs in the monitor type hardware environment;

FIG.13B shows the transportation of state information when the selectTARGET command specifying the ICE type is input while the program runs in the monitor type hardware environment;

FIG.13C shows the transportation of state information when the selectTARGET command specifying the monitor type is input while the program runs in the ICE type hardware environment;

FIG.13D shows the transportation of state information when the selectTARGET command specifying the simulator type is input while the program runs

in the ICE type hardware environment;

FIG.13E shows the transportation of state information when the selectTARGET command specifying the monitor type is input while the program runs in the simulator type hardware environment;

FIG.13F shows the transportation of state information when the selectTARGET command specifying the ICE type is input while the program runs in the simulator type hardware environment;

FIG.14A shows breakpoint addresses;

FIG.14B shows an interrupt signal generation condition;

FIG.14C shows the trace data;

FIG.14D shows information used for the breakpoint management function;

FIG.14E shows information used for the trace data accumulation size management function;

FIG.14F shows information used for the interrupt generation condition management function;

FIG.14G shows I/O mapping information used for the I/O mapping information management function;

FIG.15 is a flowchart of the procedure for the selectTARGET command in the present embodiment;

FIG.16 is a flowchart of the procedure for the targetASSIGN command in the present embodiment;

FIG.17 is a flowchart of the procedure for the IF-break command in the present embodiment; and

FIG.18 is a flowchart of the procedure for the switch (var) command in the present embodiment.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0027] The debugging apparatus of the present invention is composed of host computer 1, which is a general-purpose computer, connected to ICE control board 22 and serial transfer port 31. FIG.1A shows an appearance of the debugging apparatus of the present invention.

[0028] Prototype 30 of an electrical appliance is called the monitor type hardware environment. Prototype 30 includes a ROM which stores a debug target program. The debug target program of prototype 30 is under control of host computer 1. The start and end of the operation of the debug target program are performed with instructions from the host computer sent via serial line 40. Host computer 1 reads data from storages of prototype 30, such as memories and registers. The read data is also dealt with as the state information.

[0029] Evaluation board 20 also runs the debug target program. The debug target program of evaluation board 20 is also under control of host computer 1. The start and end of the operation of the debug target program are performed with instructions from the host computer sent via parallel line 28. Host computer 1 reads data from storages of evaluation board 20, such as memories and registers. The read data is also dealt with as the state information.

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[0030] FIG.1B is a block diagram showing the hardware construction of the debugging apparatus of the present invention. As shown in the drawing, host computer 1 is a general-purpose computer including a CPU, display 2, a memory, a hard disk, keyboard 3, ICE control board 22, and serial transfer port 31. Host computer 1 is connected to evaluation board 20, and prototype 30 respectively via ICE control board 22 and serial transfer port 31.

[0031] FIG.2A shows the hardware construction of prototype 30. As shown in the drawing, prototype 30 includes processor 33, memory 34, and peripheral I/O register set 35.

[0032] Processor 33 includes an instruction read circuit, a decoder, a calculator, a register set, and a program counter. The instruction read circuit reads machine-language instructions from the debug target program one at a time. The decoder decodes the machine language instructions. The calculator performs a calculation if a read instruction is an operation instruction. The program counter notifies the instruction read circuit of destinations into which instructions are stored. Processor 33 also includes dedicated terminal 39. Processor 33 reads operation state information and outputs the information to host computer 1 via dedicated terminal 39 when processor 33 receives a certain instruction signal via dedicated terminal 39.

[0033] Memory 34 stores monitoring program 36 and debug target program 37 and includes work area 38. When prototype 30 is activated, processor 33 runs debug target program 37. Debug target program 37 includes monitoring instructions which instruct processor 33 to branch to monitoring program 36 when data is input to dedicated terminal 39.

[0034] Monitoring program 36, on receiving data via dedicated terminal 39, allows control to branch from debug target program 37 to monitoring program 36.

[0035] Peripheral I/O register set 35 hold values of peripheral I/O devices, such as a serial interface, a parallel interface, an interrupt controller, an A/D converter, a D/A converter, and a timer counter. It is possible for processor 33 to fetch an arbitrary value of an arbitrary peripheral I/O device since values of the peripheral I/O devices are respectively stored in the registers making up peripheral I/O register set 35.

[0036] FIG.2B shows the hardware construction of evaluation board 20. compared with prototype 30, it is found that processor 33 is replaced by ICE chip 23. Evaluation board 20 also includes memory 24 and peripheral I/O register set 25.

[0037] Memory 24 includes a supervisor space and a user space. The supervisor space includes supervisor program 26 and debug information area 27. The user space includes debug target program 37 and work area 38.

[0038] Peripheral I/O register set 25 is composed of registers which hold values of corresponding peripheral I/O devices.

[0039] Supervisor program 26 includes a breakpoint setting tool, a trace tool, and an interrupt setting tool. The breakpoint setting tool sets breakpoints, where the breakpoint indicates a point where an interrupt signal is generated, or a point where an operation stops. The trace tool accumulates addresses of instructions executed by ICE chip 23. The interrupt setting tool monitors whether a certain condition set by the operator is met, and if the condition is met, generates an interrupt signal.

[0040] Debug information area 27 is an area in the memory which is used as a work area by supervisor program 26. Debug information area 27 stores breakpoint addresses, breakpoint information, trace data, and interrupt signal generation condition information. The breakpoint information indicates whether the breakpoint is effective. The trace data is composed of a plurality of accumulated addresses of instructions. The interrupt signal generation condition information indicates a certain condition set by the operator for generating interrupt signals.

[0041] FIG.14A shows breakpoint addresses. "BREAK POINT(1)=0x0020" indicates that the first breakpoint is set in an area with a certain size specified by address 0x0020. "BREAK_POINT (2)=0x0250" indicates that the second breakpoint is set in an area with a certain size specified by address 0x0250. "BREAK_POINT(3)=0x0300" indicates that the third breakpoint is set in an area with a certain size specified by address 0x0300. Such breakpoint addresses, which are set by the operator, are written in memory 24 by the breakpoint setting tool of supervisor program 26.

[0042] FIG.14B shows an interrupt signal generation condition. In the drawing, "CONDITION(1)=20cycle, Int3" indicates that an instruction is executed for 20 cycles then the third interrupt signal is generated, where a cycle representing a unit instruction execution time. "CONDITION(2)=150cycle,Int5" indicates that an instruction is executed for 150 cycles then the fifth interrupt signal is generated. Such interrupt signal generation conditions are written into memory 24 by the interrupt signal generating tool of supervisor program 26 which is activated by debug target program 37 when the operator sets the interrupt generation while debugging debug target program 37.

[0043] FIG.14C shows the trace data. The trace data shows the history of executed instructions, and "0x0000, 0x0001, 0x0002, 0x0003, 0x0004, 0x0005," indicates, for example, that ICE chip 23 has executed the machine-language instructions of debug target program 37 which are stored in the areas respectively specified by addresses 0x0000, 0x0001, 0x0002, 0x0003, 0x0004, and 0x0005. Such trace data is written in memory 24 by the trace tool of supervisor program 26 which is executed by processor 33 when the operator inputs the trace command while debugging debug target program 37 in the ICE type hardware environment.

[0044] Work area 38 is a work area used by debug target program 37.

[0045] FIG.3 shows internal layers of host computer 1. As shown in the drawing, host computer 1 is divided into application layer 11, operating system layer 12, BIOS (Basic Input/output System) layer 13, and physical layer 14, which make up a standard construction of a general-purpose computer. Application layer 11 includes simulator 10. This indicates that simulator 10 is an application program that runs on an operating system. ICE control board 22 and serial transfer port 31 exist in physical layer 14. A dedicated device driver 21 in the BIOS layer is connected to ICE control board 22.

[0046] Since simulator 10 exists in application layer 11, it is required to use the format of application layer 11 to access the simulator type hardware environment. Device driver 21 exists in BIOS layer 13. Thus, it is required to use the format of BIOS layer 13 to access the ICE type hardware environment. Since serial transfer port 31 exists in physical layer 14, it is required to use the format of physical layer 14 to access the monitor type hardware environment.

[0047] Accordingly, when parameters are transferred among the hardware environments, the formats should be changed according to the layers of the target hardware environments.

[0048] Parameters should be transferred to simulator 10 in the formats of arguments since simulator 10 is an application program in application layer 11. Parameters should be transferred to device driver 21 in the formats of commands since device driver 21 is in BIOS layer 13. Parameters should be transferred to serial transfer port 31 through I/O ports since serial transfer port 31 is in physical layer 14.

[0049] The ICE, monitor, and simulator type hardware environments are respectively assigned identifiers TARGET1, TARGET2, and TARGET3 which are registered in an identifier table (not shown in the drawings).

[0050] FIG.4 shows the sub-layers in application layer 11 which have the function of synthesizing the formats of hardware environments.

[0051] Target dependent layer 53 converts the various data formats of the other layers (hardware environments) into the format of arguments.

[0052] Target interconnect layer 52, including a shared work area in which data with the format of arguments is stored, allows the data to be shared by the three hardware environments.

[0053] Debug core layer 51 has the function as a symbolic debugger.

[0054] User interface layer 50 provides the function as a man-machine interface. For this purpose a standard input/output library (not shown in the drawings) of operating system layer 12 is used. User interface layer 50 displays a message on the screen urging the operator to input a command. In doing so, the standard input/output library of operating system layer 12 is used. When the operator inputs a command responding to the message, user interface layer 50 allows debug core layer 51 and other sub-layers to interpret and execute the

command. User interface layer 50 then displays the execution results on the screen using the standard input/output library.

[0055] FIG.5 shows the contents of the sub-layers: debug core layer 51, target interconnect layer 52, and target dependent layer 53.

[0056] As shown in the drawing, debug core layer 51 includes symbol address map 71, command interpreter 72, and command conversion routine 73.

[0057] Symbol address map 71 is information indicating the relation between symbols and addresses in the memory, where symbols represent variables, libraries and the like used in the source program. More specifically, symbol address map 71 is composed of memory sizes, variable types, identification numbers of the lines which include source codes, and line information which indicates addresses of execution codes corresponding to the lines.

[0058] Command interpreter 72 analyzes the commands input by the operator and then sent to user interface layer 50, and notifies command conversion routine 73 of the contents of the commands. FIG.6A shows such commands which are called debug commands.

[0059] The commands shown in FIG.6A, except the selectTARGET command, have been used conventionally. These commands, however, are differently used in the present embodiment in that these commands specify a target hardware environment with a corresponding identifier (any of TARGET1, TARGET2, and TARGET3).

[0060] The run command instructs the target hardware environment to start running the debug target program starting from an address which is specified in the command as an operand.

[0061] The stop command instructs the target hardware environment to stop running the debug target program.

[0062] The step command instructs the target hardware environment to sequentially execute the instructions written in the debug target program starting from an address which is specified in the command as an operand.

[0063] The setBP command instructs the target hardware environment to set a breakpoint at an address which is specified in the command as an operand, where the setting of the breakpoint indicates the writing of an instruction for generating an interrupt signal into debug target program 37, or indicates the storing of an address of an operation stop in a certain register of the processor. In the present embodiment, when the instruction for generating an interrupt signal is written into debug target program 37, the address of the instruction is also written in a memory of the current hardware environment.

[0064] The clrBP command instructs the target hardware environment to delete a breakpoint specified by operand "breakNo." In case the breakpoint is the instruction for generating an interrupt signal, the address of the instruction is also deleted.

[0065] The setINT command instructs the target hard-

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ware environment to monitor whether an instruction is executed for number of cycles specified by operand "CycleNumber" and to generate the interrupt signal specified by operand "intNO." after the instruction is executed for 20 cycles, where a cycle representing a unit instruction execution time.

[0066] The readMEM command instructs the target hardware environment to read data from an area ranging from "s_address" to "e_address" which are operands in the command.

[0067] The readREG command instructs the target hardware environment to read data from a register specified by operand "register" of the command.

[0068] The writeMEM command instructs the target hardware environment to write data, which is specified by operand "value1" of the command, into an area specified by operand "address" of the command.

[0069] The writeREG command instructs the target hardware environment to write data, which is specified by operand "value2" of the command, into a register specified by operand "register" of the command.

[0070] Variables may be used as operands in the readMEM, readREG, writeMEM, and writeREG commands. When a variable is used in such a command, command interpreter 72 refers to symbol address map 71 to specify an address or a register corresponding to the variable. Command interpreter 72 then sends the command to the target hardware environment via target interconnect layer 52.

[0071] The TRACE command instructs the target hardware environment to accumulate the addresses of the instructions which have been executed the hardware environment.

[0072] The selectTARGET command instructs the target hardware environment to transfer the operation state information, which is stored in the storages of the target hardware environment, to another hardware environment, and instructs that the debug commands should be issued to the other hardware environment. When the operation state information is transferred, data in the storages, namely, content of work area 38, contents of registers, a breakpoint, interrupt signal generation condition information, contents of peripheral I/O registers, and trace data, is transferred separately. Command interpreter 72 issues sub-commands, such as copyMEM, copyREG, copyBP, copyINT, copyI/O, and copyTRACE_DATA, to achieve such separate transfers.

[0073] The copyMEM sub-command instructs target interconnect layer 52 to transfer the contents of work area 38 of the target hardware environment to another hardware environment which is specified by the selectTARGET command. The copyMEM sub-command may also specify a start address and an end address of an arbitrary area to instructs target interconnect layer 52 to transfer the contents of the arbitrary area of the target hardware environment to another hardware environment. The copyMEM sub-command may also include a

switch indicating whether to transfer the whole contents of the memory to another hardware environment.

[0074] The copyREG sub-command instructs target interconnect layer 52 to transfer the contents of the register set of the target hardware environment to another hardware environment which is specified by the selectTARGET command.

[0075] The copyBP sub-command instructs target interconnect layer 52 to transfer the breakpoint address of the target hardware environment to another hardware environment which is specified by the selectTARGET command.

[0076] The copyINT sub-command instructs target interconnect layer 52 to transfer the interrupt signal generation condition information of the target hardware environment to another hardware environment which is specified by the selectTARGET command.

[0077] The copyI/O sub-command instructs target interconnect layer 52 to transfer the contents of all the peripheral I/O registers of the target hardware environment to another hardware environment which is specified by the selectTARGET command.

[0078] The copyTRACE_DATA instructs target interconnect layer 52 to transfer the trace data of the target hardware environment to another hardware environment which is specified by the selectTARGET command.

[0079] The following is a continued description of the components of debug core layer 51.

[0080] Command conversion routine 73 converts commands interpreted or automatically issued by command interpreter 72 into function call codes.

[0081] Command conversion routine 73 converts, for example, the readMEM command, which is one of the instructions for reading state information, into function call code "TCI_get mem(adr,length,unit,image)," where "TCI" stands for Target Core Interface, indicating that the present function call code is used between debug core layer 51 and target interconnect layer 52. As is understood from this, the function call codes are used only in limited layers. "get_mem" of the above function call code indicates that a value should be obtained from a memory. Each of "adr," "length," "unit," and "image" is an argument. Argument "adr" indicates a start address. Argument "length" indicates the length of the obtained data. Argument "unit" indicates a unit used in obtaining data, such as byte, word, and double-word. Argument "image" indicates a target area into which the data is transferred from the memory.

[0082] In the above example, when command interpreter 72 interprets an input command as the readMEM command, an instruction by a corresponding function call code is sent from debug core layer 51 to target interconnect layer 52. A hardware environment reading the data is not specified in the function call code. That means, the definition of the function call code is of an abstract level.

[0083] Command conversion routine 73 converts, for

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example, the writeREG command, which is one of the instructions for writing state information, into function call code "TCI_set REG(regs,mask)." "set_REG" of the above function call code indicates that an immediate value should be set. Each of "regs" and "mask" is an argument. Argument "regs" indicates an array name of one of array variables in the shared work area which respectively hold values of registers, such as a general purpose register, a program counter, a state register, a data register, and an address register. Argument "mask" indicates a bit pattern for masking which specifies which array elements in the array variable specified by the argument "regs" are set in the processor in the target hardware environment and which array elements are not set.

[0084] Similarly, command conversion routine 73 converts the run, stop, step, setBP, clrBP, SetINT, readREG, writeMEM, and TRACE commands respectively into function call codes "TCI_run," "TCI_stop," "TCI_step," "TCI_setBP," "TCI_clrBP," "TCI_SetINT," "TCI_read_REG," "TCI_write_MEM," and "TCI_TRACE" and sends the function call codes to target interconnect layer 52.

[0085] Each sub-command is converted into a pair of function call codes: "TCI_getxxx" for instructing the first hardware environment (source target hardware environment) to read the state information from a storage, and "TCI_setxxx" for instructing the second hardware environment (destination target hardware environment) to write the state information into a storage.

[0086] FIG.8 shows the sub-commands and the corresponding function call codes.

[0087] As shown in the drawing, the copyMEM sub-command is converted into two function call codes:

"TCI_get_mem(adr,length, unit,image)" and
"TCI_set_mem(adr,length,unit,image)."

[0088] Function code "TCI_get_mem(adr, length, unit, image)" instructs the source target hardware environment to read data from work area 38.

[0089] Function code "TCI_set_mem(adr, (adr, length, unit,image)" instructs the destination target hardware environment to write the data into work area 38.

[0090] As shown in the drawing, only function call codes "TCI_get_reg (regs,mask)," "TCI_set_reg (regs, mask)," "TCI_get INT (cycle, intkind)," "TCI_set_INT (cycle,intkind)" have two arguments and other function call codes, which transfer data between memories, have four arguments. Note that peripheral I/O register sets 25 and 35 can be accessed through memories.

[0091] Here, the function call codes corresponding to the copyBP sub-command are described. Generally, breakpoints are specified by addresses of machine-language instructions in the debug target program. For specifying such addresses, arguments "length" and "unit" are not necessary. In the present embodiment, however, so-called "area break" is considered, in which

an area effective as the breakpoint can be specified. Arguments "adr," "length," "unit," and "image," including the specifications of the length of the data for the breakpoint and the unit of the data, make it possible to use the area break.

[0092] In function call codes "ICI_get_INT (cycle,intkind)" and "TCI_set_INT(cycle,intkind)" corresponding to the copyINT sub-command, argument "cycle" indicates an integral multiple of a unit instruction execution time and argument "intkind" indicates a signal number of the interrupt signal to be generated.

[0093] Target interconnect layer 52, as shown in FIG. 5, is composed of code conversion routine 74, work area analysis module 75, and shared work area 77. Of these, code conversion routine 74 and shared work area 77 are described now and work area analysis module 75 will be described later.

[0094] Code conversion routine 74 rewrites the function call codes (high function call codes) to low function call codes which specifies the destination target hardware environment.

[0095] Suppose the first hardware environment is monitor type and the second hardware environment is simulator type. An example is given below under this condition. Suppose command conversion routine 73 has converted the copyMEM sub-command into high function code "TCI_get_mem(adr,length,unit,image)" which instructs the source target hardware environment to read data from work area 38. Code conversion routine 74 converts the high function call code into low function call code "MON_get_mem(adr,length,unit,image)," specifying the monitor type hardware environment as the source target hardware environment.

[0096] Code conversion routine 74 then converts high function call code "ICI_set_mem (adr,length, unit, image)" into low function call code "SIM_set_mem (adr, length, unit, image)," specifying the simulator type hardware environment as the destination target hardware environment. After the conversion, code conversion routine 74 calls a function using the converted low function call codes.

[0097] Code conversion routine 74 performs similar conversions against other function call codes as shown in FIG.8. FIG.9 shows the high function call codes and corresponding low function call codes.

[0098] When rewriting the function call codes, code conversion routine 74 identifies the source target hardware environment and destination target hardware environment. For identifying the source target hardware environment, code conversion routine 74 refers to the identifier table. For identifying the destination target hardware environment, code conversion routine 74 receives the selectTARGET command from command interpreter 72 and refers to an operand of the command.

[0099] Shared work area 77 is a work area which is shared by all the hardware environments and an area of shared work area 77 may be specified by argument "image."

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[0100] Target dependent layer 53 is composed of simulator 10, monitor control layer 61, and ICE control layer 62.

[0101] Simulator 10 is an application program. FIG. 2C shows the construction of simulator 10. As shown in the drawing, simulator 10 is composed of processor simulation routine 95, memory simulation routine 96, and I/O register simulation routine 97.

[0102] Processor simulation routine 95 simulates the function of processor 33.

[0103] Memory simulation routine 96 stores, as memory 24 does, supervisor program 26, debug information area 27, debug target program 37, and work area 38. Judged from this construction, the bug analysis ability of the simulator type hardware environment is almost the same as that of the ICE type hardware environment.

[0104] I/O register simulation routine 97 simulates the function of peripheral I/O register set 35.

[0105] Processor simulation routine 95, memory simulation routine 96, and I/O register simulation routine 97 are activated when code conversion routine 74 calls a function using low function call codes specifying the simulator type. When code conversion routine 74 calls a function with low function call code "SIM_get_mem (adr, length, unit, image)," processor simulation routine 95 reads data from an area in memory simulation routine 96 specified by start address "adr" in units specified by "unit," the data having a length specified by "length." Processor simulation routine 95 then stores the data into an area of shared work area 77 specified by "image."

[0106] When code conversion routine 74 calls a function with low function call code "SIM_set_mem (adr, length, unit, image)," processor simulation routine 95 reads data from an area of shared work area 77 specified by "image" in units specified by "unit," the data having a length specified by "length." Processor simulation routine 95 then writes the data into an area in memory simulation routine 96 specified by start address "adr."

[0107] Monitor control layer 61 controls the operation of the debug target program in prototype 30 and accesses the storages in prototype 30, such as memories and registers. Thus, monitor control layer 61 activates the debug target program or reads/writes data from/into the storages with a desired timing.

[0108] Monitor control layer 61 achieves the above control of the data reading/writing by performing certain communications sequences with monitoring program 36 via serial transfer port 31, dedicated terminal 39, and serial line 40. Debug core layer 51 performs such a communications sequence when code conversion routine 74 calls a function.

[0109] FIG. 10A shows the control of the data reading by monitor control layer 61. As shown in the drawing, monitor control layer 61 performs a communications sequence to control the data reading when code conversion routine 74 calls a function with low function call code "MON_get mem (adr, length, unit, image)." In the communications sequence, monitor control layer 61

transmits/receives the packets, which are shown in (2) of the drawing, according to the protocol as shown in (1) of the drawing.

[0110] Each of the three types of packets shown in (2) of FIG. 10A, namely, packets "MEMREAD," "ACK," "UNIT," and "DATA," has eight bytes.

[0111] The first byte (denoted as byte 0) of packet "MEMREAD" is assigned to field "CMD" in which a command type is specified. The second byte (denoted as byte 1) is assigned to field "UIT" in which a unit (byte, word, double-word, etc.) used in reading data from a memory is specified. The third and fourth bytes (denoted as bytes 2 and 3) are assigned to field "SIZE" in which a length of data to be read from a memory is specified. The fifth byte to the eighth byte (denoted as bytes 4 to 7) are assigned to field "ADRS" in which an address of a memory from which data is read is specified.

[0112] The first byte of packet "ACK" indicates a type of an error which has occurred in monitoring program 36.

[0113] FIG. 11A is a flowchart of the procedure of the communications sequence to control reading data from memories, which is performed by monitor control layer 61.

[0114] When code conversion routine 74 calls a function with low function call code "MON_get_mem (adr, length, unit, image)," monitor control layer 61 generates a transmission packet "MEMREAD" by setting each field. More specifically, monitor control layer 61 writes an identification code of the MEMREAD command into field "CMD," writes a code of unit name specified by argument "unit" into field "UIT," writes a data length specified by argument "length" into field "SIZE," and writes a read-target address of argument "adr" into field "ADRS" (step S1). Monitor control layer 61 transmits the generated transmission packet to monitoring program 36 via serial line 40 (step S2). Monitor control layer 61 then waits for reception packet "ACK" (step S3). If monitor control layer 61 receives reception packet "ACK," monitor control layer 61 judges whether the first byte of reception packet "ACK" indicates an error (step S4). If it indicates an error, monitor control layer 61 returns to step S2 to re-transmit the generated transmission packet; if it does not indicate an error, monitor control layer 61 proceeds to step S5. In step S5, monitor control layer 61 sets variable i to "1." In step S6, monitor control layer 61 sets variable n to the specified data length divided by the packet size (eight bytes). Here, variable i indicates the number of reception packets "DATA" having been processed and variable n indicates the total number of reception packets "DATA."

[0115] After setting the above variables to above initial values, monitor control layer 61 waits for reception packets "DATA" (step S7). If monitor control layer 61 receives reception packets "DATA," monitor control layer 61 stores eight-byte data of each reception packet in an area of shared work area 77 specified by argument "image" (step S8). monitor control layer 61 then compares

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variable *i* with variable *n* to judge if they are equal (step S9); if not equal, monitor control layer 61 increments variable *i* (step S10) then goes to step S7.

[0116] Steps S7-S10 are repeated until monitor control layer 61 judges that variable *i* is equal to variable *n* in step S9.

[0117] During the repeated operations of steps S7-S10, data in prototype 30 is transferred to monitor control layer 61 eight bytes by eight bytes via serial transfer port 31, serial line 40, and dedicated terminal 39. The transferred data is accumulated in an area of shared work area 77 specified by argument "image." When the above operation is repeated *n* times, data with the length specified by argument "length" has been stored in the area of shared work area 77 specified by argument "image."

[0118] After data is transferred from memory 34 to shared work area 77, it is possible to transfer the data to simulator 10 and ICE control layer 62. That is, when code conversion routine 74 calls a function with low function call code "SIM_set_mem(adr,length,unit,image)" at this stage, the data is written into an area of memory simulation routine 96 specified by argument "adr."

[0119] Monitor control layer 61 repeatedly performs the communication sequence to transfer other pieces of state information of the storages of prototype 30, namely, contents of other registers, a breakpoint, interrupt signal generation condition information, contents of peripheral I/O registers, and trace data, into memory simulation routine 96 via shared work area 77.

[0120] FIG.10B shows the control of the data writing by monitor control layer 61. As shown in the drawing, monitor control layer 61 performs a communications sequence to control the data writing when code conversion routine 74 calls a function with low function call code "MON_set mem(adr,length,unit,image)." In the communications sequence, monitor control layer 61 transmits/receives the packets, which are shown in (2) of the drawing, according to the protocol as shown in (1) of the drawing.

[0121] Each of the three types of packets shown in (2) of FIG.10B, namely, packets "MEMWRITE," "ACK1," "ACK2," and "DATA," has eight bytes.

[0122] The first byte (denoted as byte 0) of packet "MEMWRITE" is assigned to field "CMD" in which a command type is specified. The second byte (denoted as byte 1) is assigned to field "UIT" in which a unit (byte, word, double-word, etc.) used in writing data into a memory is specified. The third and fourth bytes (denoted as bytes 2 and 3) are assigned to field "SIZE" in which a length of data to be written into a memory is specified. The fifth byte to the eighth byte (denoted as bytes 4 to 7) are assigned to field "ADRS" in which an address of memory 34 into which data is written is specified.

[0123] The first byte of packets "ACK1" and "ACK2" indicates a type of an error which has occurred in monitoring program 36.

[0124] FIG.11B is a flowchart of the procedure of the communications sequence to control writing of data into a memory, which is performed by monitor control layer 61.

[0125] When code conversion routine 74 calls a function with low function call code "MON_set_mem (adr, length,unit,image)," monitor control layer 61 generates a transmission packet "MEMWRITE" by setting each field. More specifically, monitor control layer 61 writes a code representing the MEMWRITE command into field "CMD," writes a code representing a unit name of argument "unit" into field "UIT," writes a data length of argument "length" into field "SIZE," and writes a write-target address of argument "adr" into field "ADRS" (step S11). Monitor control layer 61 transmits the generated transmission packet to monitoring program 36 via serial line 40 (step S12). Monitor control layer 61 then waits for reception packet "ACK" (step S13). If monitor control layer 61 receives reception packet "ACK," monitor control layer 61 judges whether the first byte of reception packet "ACK" indicates an error (step S14). If it indicates an error, monitor control layer 61 returns to step S12 to re-transmit the generated transmission packet; if it does not indicate an error, monitor control layer 61 proceeds to step S15. In step S15, monitor control layer 61 sets variable *j* to "1." In step S16, monitor control layer 61 sets variable *n* to the specified data length divided by the packet size (eight bytes). Here, variable *j* indicates the number of transmission packets "DATA" having been processed and variable *n* indicates the total number of transmission packets "DATA."

[0126] After setting the above variables to above initial values, monitor control layer 61 reads eight-byte data from an area of shared work area 77 specified by argument "image," the eight-byte data ranging from byte $(8 \times (j-1))$ to byte $(8 \times j - 1)$. In the first operation in this step, for example, the eight-byte data ranges from byte 0 to byte 7 since $j=1$. monitor control layer 61 then writes the eight-byte data into field "DATA" of a transmission packet "DATA" (step S18). monitor control layer 61 transmits the packet (step S19). monitor control layer 61 then compares variable *j* with variable *n* to judge if they are equal (step S20); if not equal, monitor control layer 61 increments variable *j* (step S21) then goes to step S18.

[0127] Steps S18-S21 are repeated until monitor control layer 61 judges that variable *j* is equal to variable *n* in step S20.

[0128] During the repeated operations of steps S18-S21, data in shared work area 77 is transferred to memory 34 eight bytes by eight bytes via serial transfer port 31, serial line 40, and dedicated terminal 39. The transferred data is accumulated in memory 34. When the above operation is repeated *n* times, data with the length specified by argument "length" has been stored in memory 34.

[0129] Monitor control layer 61 repeatedly performs the communication sequence to transfer other pieces of state information of shared work area 77, namely, con-

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tents of other registers, a breakpoint, interrupt signal generation condition information, contents of peripheral I/O registers, and trace data, into a storage of prototype 30.

[0130] It is possible to transfer data of simulator 10 and ICE control layer 62 from shared work area 77 to memory 34 by writing the data in shared work area 77 in advance before code conversion routine 74 calls a function using low function call code "MON_set_mem (adr,length,unit,image)."

[0131] ICE control layer 62 controls ICE chip 23 in evaluation board 20. That is, ICE control layer 62 controls the debug target program and accesses the storages, such as memories and registers, in evaluation board 20. Thus, ICE control layer 62 activates the debug target program and writes data from the storages in evaluation board 20 into the debug target program with a desired timing.

[0132] ICE control layer 62 achieves the above control of the data reading/writing by issuing the BIOS command to device driver 21 when code conversion routine 74 calls a function with a low function call code specifying the ICE type hardware environment as the destination target hardware environment.

[0133] FIG. 12A shows the control of the data reading by ICE control layer 62. As shown in the drawing, ICE control layer 62 issues BIOS command "MEM_READ (adrs,type,num)" to device driver 21 when code conversion routine 74 calls a function with low function call code "ICE_get_mem (adr,length,unit, image)."

[0134] The BIOS command includes the following parameters: "adrs" for indicating a read target address of debug target program 37 in evaluation board 20; "type," set by device driver 21, for indicating a unit of data reading in evaluation board 20 which is used in evaluation board 20; and "num" for indicating the number of "words," the data length of each of the "words" being equal to the unit specified by parameter "type," the value of "num" being equal to the value of argument "length" divided by the value of argument "unit" when code conversion routine 74 calls a function.

[0135] ICE control layer 62 issues BIOS command "MEM_READ(adrs,type,num)" to device driver 21 with the above described parameters. After issuing the command, ICE control layer 62 waits for device driver 21 to output a result. ICE control layer 62 receives the result as a value read from an area in memory 24 specified by argument "adr" in evaluation board 20, then stores the value into an area in shared work area 77 specified by parameter "adrs."

[0136] FIG. 12B shows the control by ICE control layer 62 when ICE control layer 62 writes data into debug target program 37 in evaluation board 20. ICE control layer 62 issues BIOS command "MEM_WRITE(adrs,type,num)" to device driver 21 When code conversion routine 74 calls a function with function call code "ICE_set_mem(adr,length,unit,image)." ICE control layer 62 then outputs a value in an area of shared work

area 77 specified by argument "adr" to device driver 21 as a write target value.

[0137] Parameter "adrs" of the BIOS command indicates a write target address of debug target program 37 in evaluation board 20. Parameter "type" indicates a unit of data writing.

[0138] ICE control layer 62 issues BIOS command "MEM_WRITE(adrs,type,num)" to device driver 21 with the above described parameters.

[0139] Device driver 21 sets storages for storing addresses, sizes, and operation types in evaluation board 20, according to the BIOS command issued by ICE control layer 62.

[0140] The reason for setting such storages is that ICE chip 23 interprets the contents of the storages as instructions from host computer 1 and operates according to the interpretation, such as reading/writing data from/to memories and setting breakpoints.

[0141] Device driver 21, on receiving BIOS command "MEM_READ(adrs,type,num)," stores the value specified by parameter "adrs" into the storage for addresses, stores the value specified by parameter "num" into the storage for sizes, and stores operation type "read" into the storage for operation types. ICE chip 23 reads data from an area in memory 24 specified by parameter "adrs" in the unit specified by parameter "num." device driver 21 outputs the read data to ICE control layer 62 as the state information of memory 24 in evaluation board 20.

[0142] Device driver 21, on receiving BIOS command "MEM_WRITE(adrs,type,num)," stores the value specified by parameter "adrs" into the storage for addresses, stores the value specified by parameter "num" into the storage for sizes, and stores operation type "write" into the storage for operation types. Device driver 21 outputs data from an area of shared work area 77 specified by argument "image" which has been transferred from monitor control layer 61. ICE chip 23 writes the data into an area in memory 24 specified by parameter "adrs" in the unit specified by parameter "num."

[0143] The operation of the present debugging apparatus with the above construction is described below. FIG. 7 shows messages output by user interface layer 50.

[0144] When the debugging apparatus is activated, user interface layer 50 outputs message p1 shown in the drawing, "+HARDWARE ENVIRONMENT IS SET TO TARGET1. TARGET1 IS MONITOR TYPE." User interface layer 50 then outputs message "+INPUT COMMAND" and displays a prompt for urging the user to input a command.

[0145] Here, suppose the user inputs "readMEM 0x0100,16" on keyboard 3. User interface layer 50 transfers the input command to debug core layer 51 so that debug core layer 51 interprets and executes the command.

[0146] Command conversion routine 73 converts the command into function call code "Tcl_read_mem

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[0164] User interface layer 50 displays a message "PROGRAM STOPPED AT 0x0123 OF TARGET1" and displays a prompt for urging the user to input a command.

[0165] Here, suppose the user inputs "selectTARGET" on keyboard 3. The following is a description of the operation for the selectTARGET command.

[0166] FIGs. 13A-13F show the transportation of commands, function call codes, and state information in the layers in the debugging apparatus, as shown in FIGs. 4 and 5.

[0167] FIG. 13A shows the transportation of state information when the selectTARGET command specifying the simulator type hardware environment as the destination target hardware environment is input while the program runs in the monitor type hardware environment. Each layer includes the function call codes and commands used under the condition. The arrows indicate the direction of these function call codes and commands.

[0168] The operation of command interpreter 72 related to the interpretation of the selectTARGET command is described below with reference to FIGs. 13A and 15.

[0169] It is supposed that the user inputs the selectTARGET command on keyboard 3 specifying the simulator type while the program runs in the monitor type hardware environment.

[0170] User interface layer 50 is waiting for the user to input a command by displaying a prompt, in step S81 in the flowchart of FIG. 15. When the user inputs a command, command interpreter 72 interprets the input command in step S82. command interpreter 72 then judges whether the operation code is "selectTARGET" in step S83. If it is, command interpreter 72 instructs the first hardware environment (source target hardware environment) to stop running the program. Command interpreter 72 issues sub-commands copyMEM, copyREG, copyBP, copyINT, copyI/O, and copyTRACEDATA in steps S85-S90, respectively (see arrow y1 in FIG. 13A).

[0171] Command conversion routine 73 converts, for example, sub-command "copyMEM" into two high function call codes: "TCI_get_mem(adr,length, unit,image)" and "TCI_set_mem(adr,length, unit,image)" (see arrow y2 in FIG. 13A). command conversion routine 73 also converts, for example, sub-command "copyREG" into two high function call codes: "TCI_get_reg(regs,mask)" and "TCI_set_reg(regs,mask)."

[0172] Code conversion routine 74 converts the high function call codes to low function call codes specifying target hardware environments.

[0173] In this case, the source target hardware environment is the monitor type and the destination target hardware environment is the simulator type. Thus low function call codes "MON_get_mem(adr,length,unit,image)" and "SIM_set mem(adr,length,unit,image)" are generated (see arrows y3 and y4 in FIG. 13A). Code conversion routine 74 calls functions with the low func-

tion call codes.

[0174] When code conversion routine 74 calls a function with low function call code "MON_get_mem(adr,length,unit,image)," monitor control layer 61 is activated. Monitor control layer 61 reads data from prototype 30 one byte by one byte via serial transfer port 31, serial line 40, and dedicated terminal 39, as shown in the flowchart of FIG. 11A. Monitor control layer 61 accumulates the read data in an area of shared work area 77 specified by argument "image." When monitor control layer 61 repeats this process n times as specified by field "SIZE," data with the length specified by argument "length" has been stored in the area of shared work area 77 specified by argument "image" (see arrow T1 in FIG. 13A).

[0175] When code conversion routine 74 calls a function with low function call code "SIM_set_mem(adr,length,unit,image)," monitor control layer 61 transfers data, as the state information, from an area in shared work area 77 specified by argument "image" to an area in memory simulation routine 96 specified by argument "adr" (see arrow T2 in FIG. 13A).

[0176] The above process is repeated for each of the other sub-commands: copyREG, copyBP, copyINT, copyI/O, and copyTRACE_DATA. When this completes, the operation states stored in the storages of prototype 30 have been transferred to simulator 10. This indicates that the state information has been transferred from prototype 30 to simulator 10 and that simulator 10 has succeeded the operation of prototype 30. Simulator 10 resumes the operation of the program with the succeeded operation state information.

[0177] FIG. 13B shows the transportation of state information when the selectTARGET command specifying the ICE type is input while the program runs in the monitor type hardware environment. When code conversion routine 74 generates low function call code "ICE_set_mem (adr,length, unit,image)," ICE control layer 62 is activated. ICE control layer 62 issues the BIOS command to transfer the state information from an area specified by argument "image" to evaluation board 20 (see arrow T4 in FIG. 13B). This indicates that the state information has been transferred from prototype 30 to evaluation board 20 and that evaluation board 20 has succeeded the operation of prototype 30.

[0178] FIG. 13C shows the transportation of state information when the selectTARGET command specifying the monitor type is input while the program runs in the ICE type hardware environment. When code conversion routine 74 generates low function call code "ICE_get_mem (adr,length,unit,image)," ICE control layer 62 is activated. ICE control layer 62 transfers the state information from evaluation board 20 to an area specified by argument "image" (see arrow T5 in FIG. 13C).

[0179] When code conversion routine 74 generates low function call code "MON_set_mem(adr,length,unit,image)," monitor control layer 61 is activated. Monitor control layer 61 transfers the data from the area speci-

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fied by argument "image" to prototype 30 via serial line 40 (see arrow T6 in FIG.13C). This indicates that the state information has been transferred from evaluation board 20 to prototype 30 and that prototype 30 has succeeded the operation of evaluation board 20.

[0180] FIG.13D shows the transportation of state information when the selectTARGET command specifying the simulator type is input while the program runs in the ICE type hardware environment. When code conversion routine 74 generates low function call code "ICE_get_mem(adr,length,unit,image)," ICE control layer 62 is activated. ICE control layer 62 transfers the state information from evaluation board 20 to an area specified by argument "image" (see arrow T7 in FIG.13D).

[0181] When code conversion routine 74 generates low function call code "SIM_set_mem(adr,length,unit,image)," simulator 10 is activated. Simulator 10 transfers the data from the area specified by argument "image" to memory simulation routine 96 (see arrow T8 in FIG.13D). This indicates that the state information has been transferred from evaluation board 20 to simulator 10 and that simulator 10 has succeeded the operation of evaluation board 20.

[0182] FIG.13E shows the transportation of state information when the selectTARGET command specifying the monitor type is input while the program runs in the simulator type hardware environment. When code conversion routine 74 generates low function call code "SIM_get_mem(adr,length,unit,image)," simulator 10 is activated. Simulator 10 writes the state information of itself into an area of shared work area 77 specified by argument "image" (see arrow T9 in FIG.13E).

[0183] When code conversion routine 74 generates low function call code "MON_set_mem(adr,length,unit,image)," monitor control layer 61 is activated. Monitor control layer 61 transfers the data from the area specified by argument "image" to prototype 30 (see arrow T10 in FIG.13E). This indicates that the state information has been transferred from simulator 10 to prototype 30 and that prototype 30 has succeeded the operation of simulator 10.

[0184] FIG.13F shows the transportation of state information when the selectTARGET command specifying the ICE type is input while the program runs in the simulator type hardware environment. When code conversion routine 74 generates low function call code "SIM_get_mem(adr,length,unit,image)," simulator 10 is activated. Simulator 10 writes the state information of itself into an area of shared work area 77 specified by argument "image" (see arrow T11 in FIG.13F).

[0185] When code conversion routine 74 generates low function call code "ICE_set_mem(adr,length,unit,image)," ICE control layer 62 is activated. ICE control layer 62 transfers the data from the area specified by argument "image" to evaluation board 20 (see arrow T12 in FIG.13F). This indicates that the state information has been transferred from simulator 10 to evaluation board 20 and that evaluation board 20 has succeeded

the operation of simulator 10.

[0186] Arbitrary switching between the monitor type, ICE type, and simulator type hardware environments is achieved by the above described transportation of the state information.

[0187] The following is a description of work area analysis module 75, which is a component of target interconnect layer 52.

[0188] work area analysis module 75 includes a breakpoint management function, a trace data accumulation size management function, an interrupt generation condition management function, and an I/O mapping information management function. The breakpoint management function manages the memories of the hardware environments by dividing each memory into areas in which breakpoints can be set and areas in which breakpoints cannot be set. The trace data accumulation size management function manages, for each hardware environment, the sizes of the areas in which breakpoints can be set. The interrupt generation condition management function manages each hardware environment whether it has an ability to monitor whether an interrupt generation condition has been satisfied. The I/O mapping information management function manages the I/O mapping information.

[0189] work area analysis module 75 includes the breakpoint management function to deal with a case where description forms of interrupt instruction for setting breakpoint differ among the monitor type, ICE type, and simulator type. If a breakpoint is set in RAM in the source target hardware environment and the RAM corresponds to a ROM in the destination target hardware environment, for example, it is impossible to set the breakpoint in the destination target hardware environment. If the user does not know this fact in advance, the user will be embarrassed at a phenomenon in which a breakpoint becomes ineffective when the user switches the hardware environments. When this happens, the user may think this phenomenon as an error. Therefore, it is necessary for work area analysis module 75 to have a function to manage the memories of the hardware environments by dividing each memory into areas in which breakpoints can be set and areas in which breakpoints cannot be set.

[0190] FIG.14D shows information used for the breakpoint management function. The information includes: labels of the areas in which breakpoints can be set (e.g. VALID_AREA1), and the start and end addresses of the areas.

[0191] Work area analysis module 75 includes the trace data accumulation size management function to deal with a case where the memory sizes for the trace data differ among the monitor type, ICE type, and simulator type. If the source target hardware environment is simulator type and the destination target hardware environment is monitor type, for example, it is impossible to transfer all the trace data accumulated in the source target hardware environment to the destination target

hardware environment. This is because the memory of the destination target hardware environment goes short of space for storing the trace data. When this happens, a part of the trace data is lost. If the user does not know this fact in advance, the user will be embarrassed at a phenomenon in which a part of the trace data is lost. Therefore, it is necessary for work area analysis module 75 to have a function to manage, for each hardware environment, the sizes of the areas in which breakpoints can be set.

[0192] FIG. 14E shows information used for the trace data accumulation size management function. The information includes identification names (e.g. target1) for the hardware environments, and the maximum sizes of the memory areas in which breakpoints can be set.

[0193] Work area analysis module 75 includes the interrupt generation condition management function to deal with a case where some hardware environments may have an ability to monitor whether an interrupt generation condition has been satisfied and other hardware environment may not have such an ability. If the source target hardware environment is simulator type and the destination target hardware environment is monitor type, for example, the source target hardware environment may have such an ability since instruction executions can be counted by software; it is difficult for the destination target hardware environment to have such an ability unless the hardware construction is modulated for this purpose. Thus, the destination target hardware environment may not recognize the fulfillment of the interrupt generation condition. If the user does not know this fact in advance, the user will be embarrassed. Therefore, it is necessary for work area analysis module 75 to have a function to manage each hardware environment whether it has an ability to monitor whether an interrupt generation condition has been satisfied.

[0194] FIG. 14F shows information used for the interrupt generation condition management function. The information includes identification names (e.g. target1) for the hardware environments and indicates whether the hardware environment can count the number of instruction executions (cycles). "VALID" in the drawing indicates that the hardware environment can count the number of instruction executions; "INVALID" indicates that the hardware environment cannot count the number of instruction executions.

[0195] Work area analysis module 75 includes the I/O mapping information management function to deal with a case where the number of effective peripheral I/O registers differs among the monitor type, ICE type, and simulator type. If the source target hardware environment is the monitor type and destination target hardware environment is simulator type, for example, only a part of the peripheral I/O registers are available in the source target hardware environment due to slow adjustment of the hardware environment; all the peripheral I/O registers are available in the destination target hardware environment since the hardware environment is

simulated by software. Under such a condition, invalid values may be stored in the peripheral I/O registers of the destination target hardware environment. Therefore, it is necessary for work area analysis module 75 to have a function to manage the effective I/O registers for each hardware environment.

[0196] FIG. 14G shows I/O mapping information used for the I/O mapping information management function. The I/O mapping information indicates values to be set in the peripheral I/O registers of the destination target hardware environment when the corresponding peripheral I/O registers of the source target hardware environment do not have values. "I/O REGISTER_ADDR1," for example, indicates the first peripheral I/O register; "PSW=STATUS1 0x1F" indicates that value "0x1F" should be set in the first peripheral I/O register when the PSW register of the processor in the destination target hardware environment stores value "STATUS1," "PSW=STATUS2 0x2A" indicates that value "0x2A" should be set in the first peripheral I/O register when the PSW register stores value "STATUS2," and "PSW=STATUS3 0x3B" indicates that value "0x3B" should be set in the first peripheral I/O register when the PSW register stores value "STATUS3."

[0197] The following is a description of the extended selectTARGET commands.

[0198] FIG. 6B shows three major examples of the extended selectTARGET commands. The extension of a selectTARGET command is achieved by assigning a certain condition to the issue of the selectTARGET command. The three extended selectTARGET commands of FIG. 6B have different conditions.

[0199] The IFbreak command instructs the source target hardware environment to run the debug target program, and issues the selectTARGET command when the execution of the program stops at the breakpoint specified by operand "breakNo."

[0200] The targetASSIGN command allows a table specified by operand "table*" be resident in the source target hardware environment, instructs the source target hardware environment to run the debug target program, and issues the selectTARGET command based on the table. FIG. 6C shows the table. As shown in the drawing, the areas each of which is ranging the first address to the end address have corresponding destination target hardware environments.

[0201] The switch command switches the hardware environments according to the value of variable "var." In the present embodiment, the switch command has two option cases: case '*1' for variable value "*1" and case '*2' for variable value "*2." In the present case, if the variable value is "*1," hardware environment "target1" is activated; if the variable value is "*2," hardware environment "target2" is activated.

[0202] The operation procedure of command interpreter 72 for each of the three extended selectTARGET commands is described below with reference to the flowcharts of FIGs. 16-18.

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[0203] Suppose the user inputs the targetASSIGN command into user interface layer 50. Control goes to step S71 of the flowchart of FIG.16 via step S83 of FIG. 15. Command interpreter 72 judges in step S71 whether the operation code is "targetASSIGN." In this case, it is judged as yes. command interpreter 72 allows a table specified by operand "table*" be resident in the source target hardware environment in step S72. Command interpreter 72 then sets breakpoints in all the start addresses in the table, in step S73. Command interpreter 72 runs the debug target program in step S74. Command interpreter 72 monitors the debug target program to see if it has stopped at a breakpoint (step S75). If such a stop is detected, command interpreter 72 checks to see whether the address of the breakpoint matches any of the start addresses in the table (step S76). If matches, command interpreter 72 issues the selectTARGET command specifying the destination target hardware environment corresponding to the matched start address.

[0204] Suppose the user inputs the IFbreak command into user interface layer 50. Command interpreter 72 judges in step S83 in the flowchart of FIG.15 that the operation code is not "selectTARGET." Control then goes to step S71 of the flowchart of FIG.16, and command interpreter 72 judges that the operation code is not "targetASSIGN." Control then goes to step S91 of the flowchart of FIG.17. Command interpreter 72 judges in the step whether the operation code is "IFbreak." In this case, it is judged as yes. Command interpreter 72 allows operands "breakNo" and "selectTARGETtarget" be resident in the source target hardware environment in step S92. Command interpreter 72 runs the debug target program in step S93. Command interpreter 72 monitors the debug target program to see if it has stopped at a breakpoint (step S94). If such a stop is detected, command interpreter 72 checks to see whether the address of the breakpoint matches operand "breakNo" (step S96). If matches, command interpreter 72 issues the selectTARGET command specifying the destination target hardware environment which is specified by operand "selectTARGETtarget" (step S97).

[0205] Suppose the user inputs the switch(var) command into user interface layer 50. Command interpreter 72 passes through steps S83, S71, and S91 with "no." Command interpreter 72 judges in step S100 in the flowchart of FIG.18 whether the operation code is "switch(var)." In this case, it is judged as yes. Command interpreter 72 instructs debug core layer 51 to convert variable "var" into a memory address "mem_adr(var)." in step S101. Command interpreter 72 reads data from an area specified by memory address "mem_adr(var)" in step S102. Command interpreter 72 judges whether the read data matches either of "*1" and "*2" in step S103. If it matches, command interpreter 72 issues the selectTARGET command specifying the destination target hardware environment ("target1" or "target2") which corresponds to the matched value, namely, "*1" or "*2" (step S104).

[0206] As will be understood from the above description, the present embodiment enables the operator to switch the hardware environments at any state of debugging with a simple procedure, that is, by issuing the selectTARGET command. That means the operator can analyze the cause of bugs in another hardware environment without a trouble reproducing the same situation. This allows the operator to effectively use the time for developing products.

[0207] The above advantage is remarkable when bugs are found in a hardware environment, such as the monitor type, which has poor analysis functions since the hardware environment can be changed to another hardware environment with affluent analysis functions, such as the ICE type and the simulator type.

[0208] The above environment shows only one example of systems which displays best effects currently available. The present invention can be changed or modified unless such changes and modifications depart from the scope of the present invention, that is, as long as the invention includes a simple change between the hardware environments. The following are examples of such modifications.

(a) In the present embodiment, the supervisor program is stored in a memory. The supervisor program, however, may be included in debug core layer 51. Alternately, target interconnect layer 52 may be included in debug core layer 51.

(b) In the present embodiment, it is assumed that the setting of breakpoints, trace data, and interrupts are available in the destination target hardware environment. However, in case any of such functions are not possible in the destination target hardware environment, certain functions that are available may be specified.

(c) In the present embodiment, all the contents of work area 38 are transferred to the destination target hardware environment. However, only a changed part of previously transferred data may be transferred. This will lessen the load of transfer. To achieve this, the data in the stack area and the external variable area is stored in debug core layer 51 or target interconnect layer 52 as a backup. When the selectTARGET command is issued, data to be transferred is compared with the backup, and only a changed part is transferred to the destination target hardware environment. The changed part or data including the changed part may be stored in a storage.

(d) A changed part of data may be transferred to other hardware environments each time the data is changed. In such a case, the hardware environments are changed with higher speed since it is not necessary to transfer data from memory to memory.

(e) In the present embodiment, all the values of registers are transferred to the destination target hardware environment. However, only changed values

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of registers may be transferred. In such a case, the hardware environments are changed with higher speed since it is not necessary to transfer values of all the registers.

(f) The "area break" may be used if this function is available in the target hardware environments. With the area break, an area can be specified as the breakpoint.

(g) In the present embodiment, a command for switching the hardware environments according to the value of a variable is described. There may be used a command, instead of the above command, for switching the hardware environments according to the value of a parameter.

(h) A command may be used in which the change of the hardware environments, the generation of an interrupt signal, and the state of the destination target hardware environment are specified. By issuing such a command, the debug target program may be monitored in the destination target hardware environment for a specified interrupt in a specified state.

(i) A command may be used in which the change of the hardware environments, the first and the second destination target hardware environments, the change of the contents of a certain memory or a certain register, and the monitoring of the memory or register are specified. By issuing such a command, the debug target program may be monitored when the contents of the memory or register are changed in a specified hardware environment.

(j) A command including a table may be used in which the change of the hardware environments is specified, where the table shows a plurality of hardware environments and corresponding scheduled execution times. By issuing such a command, the debug target program may be monitored in specified hardware environments at specified execution times.

(k) In the present embodiment, the debug is stored in memory 24 and memory simulation routine 96. However, the debug information may be held in debug core layer 51 and target interconnect layer 52. With such an arrangement, it is virtually unnecessary to read the debug information from monitor control layer 61, ICE control layer 62, and simulator 10 of target dependent layer 53. It is also unnecessary for command conversion routine 73 to issue function call codes "TCI_get_mem," "TCI_get_reg," and "TCI_get_BP." Although the present invention has been fully described by way of examples with reference to the accompanying drawings, it is to be noted that various changes and modifications will be apparent to those skilled in the art. Therefore, unless such changes and modifications depart from the scope of the present invention, they should be construed as being included therein.

Claims

1. A debugging apparatus for verifying a program, which is to be embedded into a target machine (30), by running the program in any of the target machine (30) itself, an emulator machine (20) emulating the target machine (30), and a simulator (1) simulating the target machine (30) in terms of software, wherein

each of the target machine (30), the emulator machine (20), and the simulator (1) includes operation state information which indicates an operation state of the program and inputs and outputs the operation state information in a form unique to each of the target machine (30), the emulator machine (20), and the simulator (1), the debugging apparatus comprising:

target environment storing means for storing information of a target environment which is an identification name of any of the target machine (30), the emulator machine (20), and the simulator (1) as an environment target;
receiving means for receiving a command input by an operator;
instruction detecting means for judging whether a certain instruction is included in the command received by the receiving means;
specifying means for, when the instruction detecting means judges that the certain instruction is included in the command, specifying a target environment specified by the identification name stored in the target environment storing means as a source target environment and for specifying, as a destination target environment, one of the target machine (30), the emulator machine (30), and the simulator (1) other than the identification name stored in the target environment storing means;
reading means for reading operation state information from the source target environment;
converting means for converting the operation state information read by the reading means into operation state information written in a form unique to the destination target environment;
setting means for setting the operation state information written in the form unique to the destination target environment in the destination target environment; and
operation resuming means for resuming an operation of the program in the destination target environment.

2. The debugging apparatus of Claim 1, wherein the target machine inputs and outputs the operation state information in a first form, the emulator machine inputs and outputs the operation state information in a second form, and the simulator inputs

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and outputs the operation state information in a third form, wherein

the converting means includes:

a first converting unit for converting the operation state information from the first form to the third form when the source target environment is the target machine and the destination target environment is the simulator; and

a second converting unit for converting the operation state information from the second form to the third form when the source target environment is the emulator machine and the destination target environment is the simulator, wherein

the setting means includes:

a first setting unit for setting the operation state information in the simulator after the operation state information has been converted into the third form.

3. The debugging apparatus of Claim 2, wherein the converting means includes:

a third converting unit for converting the operation state information from the third form to the first form when the source target environment is the simulator and the destination target environment is the target machine; and
a fourth converting unit for converting the operation state information from the third form to the second form when the source target environment is the simulator and the destination target environment is the emulator machine, wherein

the setting means includes:

a second setting unit for setting the operation state information in the target machine after the operation state information has been converted into the first form; and

a third setting unit for setting the operation state information in the emulator machine after the operation state information has been converted into the second form.

4. The debugging apparatus of Claim 3, wherein the converting means includes:

a first controlling unit for instructing the first converting unit to convert the operation state information from the first form to the third form when the source target environment is the target machine and the destination target environment is the emulator machine, then instructing the fourth converting unit to convert the operation state information from the third form to the sec-

ond form; and

a second controlling unit for instructing the second converting unit to convert the operation state information from the second form to the third form when the source target environment is the emulator machine and the destination target environment is the target machine, then instructing the third converting unit to convert the operation state information from the third form to the first form.

5. The debugging apparatus of Claim 4 further comprising:

a serial transfer port for inputting and outputting the operation state information of the first form from and to a processor included in the target machine, wherein the serial transfer port is connected to the processor via a first line; and
a device driver for inputting and outputting the operation state information of the second form from and to an incircuit emulator included in the emulator machine, wherein the device driver is connected to the incircuit emulator via a second line.

6. The debugging apparatus of Claim 5, wherein the operation state information is composed of information stored in a register and a memory of the source target environment.

7. The debugging apparatus of Claim 6, wherein

the target machine, the emulator machine, and the simulator are also called target environments, wherein
the information stored in the memory is one of:

a breakpoint for instructing the processor to stop operating;
trace data which is composed of at least an address of an instruction in the program which has been executed; and
interrupt setting information for generating an interrupt signal when a certain condition set by the operator is satisfied.

8. The debugging apparatus of Claim 7 further comprising:

storage managing means for managing memories and registers of the target machine, the emulator machine, and the simulator by classifying the memories and the registers into memories and registers storing effective values and memories and registers storing ineffective values; and
rewriting means for converting ineffective val-

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ues included in operation state information into default values by referring to the storage managing means when the operation state information is read from the source target environment by the reading means, wherein

the converting means converts the operation state information into a form of the destination target environment after the rewriting means has converted the ineffective values into the default values.

9. The debugging apparatus of Claim 7 further comprising:

breakpoint setting managing means for managing areas of the memories and the registers of the target machine, the emulator machine, and the simulator by classifying the areas into areas for which a breakpoint can be set and areas for which a breakpoint cannot be set;

judging means for judging whether a breakpoint is to be set in the destination target environment by referring to the breakpoint setting managing means after the converting means has converted the operation state information into the form of the destination target environment; and

notifying means for notifying the operator that the breakpoint is not to be set in the destination target environment when the judging means judges that the breakpoint is not to be set in the destination target environment.

10. The debugging apparatus of Claim 7 further comprising:

maximum value storing means for storing a value representing the maximum number of accumulated addresses for each of the target machine, the emulator machine, and the simulator; address number recognizing means for recognizing a current number of accumulated addresses in the destination target environment; and

notifying means for notifying the operator of a difference between the current number of accumulated addresses and the maximum number of accumulated addresses.

11. The debugging apparatus of Claim 7 further comprising:

interrupt generation managing means for managing the target environments by classifying the target environments into ones which monitor a satisfaction of an interrupt generation condition and ones which do not monitor the satisfaction of the interrupt generation condition;

judging means for judging whether the destination target environment monitors the satisfaction of the interrupt generation condition by referring to the interrupt generation managing means after the converting means has converted the operation state information into the form of the destination target environment; and notifying means for notifying the operator that the destination target environment does not monitor the satisfaction of the interrupt generation condition when the judging means judges that the destination target environment does not monitor the satisfaction of the interrupt generation condition.

12. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting an instruction of monitoring a generation of an interrupt signal when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the instruction being included in the command received by the receiving means;

second interpreting means for interpreting an identification number of an interrupt signal and a corresponding destination target environment, the identification number and the corresponding destination target environment being included in the command received by the receiving means;

monitoring means for monitoring the generation of the interrupt signal in the source target environment; and

judging means for, when an interrupt signal is generated, judging whether an identification number of the generated interrupt signal matches the identification number interpreted by the second interpreting means, wherein the reading means reads the operation state information from the source target environment when the judging means judges that the identification number of the generated interrupt signal matches the identification number interpreted by the second interpreting means.

13. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting an instruction of monitoring a rewriting of one of a certain memory and a certain register when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the instruction being included in the command received

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by the receiving means;
 second interpreting means for interpreting an instruction of changing a current target environment to another target environment in case one of the certain memory and the certain register is rewritten, the instruction being included in the command received by the receiving means;
 and
 monitoring means for monitoring the rewriting of one of the certain memory and the certain register, wherein
 the reading means reads the operation state information from the source target environment, wherein
 the converting means converts the operation state information into the form of the destination target environment which is the other target environment interpreted by the second interpreting means.

14. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting an instruction of changing target environments when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the instruction being included in the command received by the receiving means;
 second interpreting means for interpreting a table which shows relation between a plurality of parts of the program and corresponding target environments, the table being included in the command received by the receiving means;
 third interpreting means for interpreting an instruction of monitoring a change of currently executed part of the program, the instruction being included in the command received by the receiving means; and
 monitoring means for monitoring the change of currently executed part of the program in the source target environment, wherein

the specifying means includes:

a destination specifying unit for specifying a destination target environment when the monitoring means detects the change of currently executed part by referring to the table interpreted by the second interpreting means, wherein the reading means reads the operation state information from the source target environment when the destination specifying unit specifies the destination target environment.

15. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting an instruction of changing target environments when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the instruction being included in the command received by the receiving means;
 second interpreting means for interpreting a table which shows relation between a plurality of variable values, a plurality of values which can be stored in one of a memory and a register, and corresponding target environments, the table being included in the command received by the receiving means;
 third interpreting means for interpreting an instruction of monitoring a change of a certain variable of the program, the instruction being included in the command received by the receiving means; and
 monitoring means for monitoring the change of the certain variable of the program in the source target environment, wherein

the specifying means includes:

a destination specifying unit for specifying a destination target environment when the monitoring means detects the change of the certain variable by referring to the table interpreted by the second interpreting means, wherein the reading means reads the operation state information from the source target environment when the destination specifying unit specifies the destination target environment.

16. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting a table which shows relation between a plurality of parameters, a plurality of parts of the program, and corresponding target environments when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the table being included in the command received by the receiving means;
 second interpreting means for interpreting an instruction of monitoring a change of a certain parameter of the program, the instruction being included in the command received by the receiving means; and
 monitoring means for monitoring the change of the certain parameter of the program in the source target environment, wherein

the specifying means includes:

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a destination specifying unit for specifying a destination target environment when the monitoring means detects the change of the certain parameter by referring to the table interpreted by the first interpreting means, wherein the reading means reads the operation state information from the source target environment when the destination specifying unit specifies the destination target environment.

17. The debugging apparatus of Claim 7 further comprising:

first interpreting means for interpreting a table which shows relation between a plurality of target environments and corresponding scheduled execution times when the instruction detecting means judges that the certain instruction is not included in the command received by the receiving means, the table being included in the command received by the receiving means; and time measuring means for measuring a current time, wherein

the specifying means includes:

a destination specifying unit for specifying a destination target environment when the current time matches one of the scheduled execution times by referring to the table interpreted by the first interpreting means, wherein the reading means reads the operation state information from the source target environment when the destination specifying unit specifies the destination target environment.

Patentansprüche

1. Vorrichtung zur Programmfehlerbeseitigung zur Verifizierung eines Programms, das in eine Zielmaschine (3a) eingebettet werden soll, indem das Programm auf irgendeiner der Zielmaschine (3a) selbst, einer Emulatormaschine, die die Zielmaschine (30) emuliert, oder einer Simulatoreinrichtung (1), die die Zielmaschine (30) im Hinblick auf Software simuliert, laufengelassen wird wobei

die Zielmaschine (30), die Emulatormaschine (20) und die Simulatoreinrichtung (1) jeweils eine Operationszustandsinformation umfasst, die einen Operationszustand des Programms angibt, und die Operationszustandsinformation in einer für die Zielmaschine (30), die Emulatormaschine (20) und die Simulatoreinrichtung (1) jeweils eindeutigen Form ein- und ausgibt, wobei die Vorrichtung zur Programmfehlerbe-

seitigung umfasst:

ein Zielumfeld-Speichermittel zum Speichern von Information über ein Zielumfeld, das einen Kennungsnamen von jeweils der Zielmaschine (30), der Emulatormaschine (20) oder der Simulatoreinrichtung (1) als ein Umfeldziel ist;

ein Empfangsmittel zum Empfang einer Kommandoeingabe durch eine Bedienerperson;

ein Befehlserfassungsmittel zum Bestimmen, ob ein gewisser Befehl in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wird;

ein Spezifizierungsmittel um, wenn das Befehlserfassungsmittel bestimmt, dass der gewisse Befehl in dem Kommando enthalten ist, ein Zielumfeld zu spezifizieren, das durch den Kennungsnamen spezifiziert ist, der in dem Zielumfeld-Speichermittel als ein Quellenzielumfeld gespeichert ist, und um als Destinationszielumfeld die Zielmaschine (30), die Emulatormaschine (30) oder die Simulatoreinrichtung (1) mit einem von dem Kennungsnamen verschiedenen zu spezifizieren, der in dem Zielumfeld-Speichermittel gespeichert ist;

Lesemittel zum Lesen der Operationszustandsinformation von dem Quellenzielumfeld;

Umwandlungsmittel zur Umwandlung der Operationszustandsinformation, die von dem Lesemittel gelesen wurde, in eine Operationszustandsinformation, die in einer für das Destinationszielumfeld eindeutigen Form geschrieben wird;

Einstellmittel zum Einstellen der Operationszustandsinformation, die in der für das Destinationszielumfeld eindeutigen Form geschrieben ist, in dem Destinationszielumfeld; und

Operationswiederaufnahmemittel zur Wiederaufnahme einer Operation des Programms in dem Destinationszielumfeld.

2. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 1, in der die Zielmaschine die Operationszustandsinformation in einer ersten Form ein- und ausgibt, die Emulatormaschine die Operationszustandsinformation in einer zweiten Form ein- und ausgibt und die Simulatoreinrichtung die Operationszustandsinformation in einer dritten Form ein- und ausgibt, wobei das Umwandlungsmittel umfasst:

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eine erste Umwandlungseinheit zur Umwandlung der Operationszustandsinformation aus der ersten Form in die dritte Form, wenn das Quellenzielumfeld die Zielmaschine ist, und das Destinationszielumfeld die Simulatoreinrichtung ist, und

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eine zweite Umwandlungseinheit zur Umwandlung der Operationszustandsinformation aus der zweiten Form in die dritte Form, wenn das Quellenzielumfeld die Emulatormaschine ist und das Destinationszielumfeld die Simulatoreinrichtung ist, wobei das Einstellmittel umfasst:

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eine erste Einstelleinheit zum Einstellen der Operationszustandsinformation in der Simulatoreinrichtung, nachdem die Operationszustandsinformation in die dritte Form umgewandelt worden ist.

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3. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 2, in der das Umwandlungsmittel enthält:

eine dritte Umwandlungseinheit zur Umwandlung der Operationszustandsinformation aus der dritten Form in die erste Form, wenn das Quellenzielumfeld die Simulatoreinrichtung und das Destinationszielumfeld die Zielmaschine ist, und

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eine vierte Umwandlungsmittel zur Umwandlung der Operationszustandsinformation aus der dritten Form in die zweite Form, wenn das Quellenzielumfeld die Simulatoreinrichtung ist und das Destinationszielumfeld die Emulatormaschine ist, wobei die Einstellmittel umfasst:

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eine zweite Einstelleinheit zum Einstellen der Operationszustandsinformation in der Zielmaschine nachdem die Operationszustandsinformation in die erste Form umgewandelt worden ist, und

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eine dritte Einstelleinheit zum Einstellen der Operationszustandsinformation in der Emulatormaschine nachdem die Operationszustandsinformation in die zweite Form umgewandelt worden ist.

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4. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 3, in der das Umwandlungsmittel umfasst:

eine erste Steuereinheit zum Befehlen der ersten Umwandlungseinheit, die Operationszustandsinformation aus der ersten Form in die dritte Form umzuwandeln, wenn das Quellen-

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zielumfeld die Zielmaschine ist und das Destinationszielumfeld die Emulatormaschine ist, daraufhin Befehlen der vierten Umwandlungseinheit, die Operationszustandsinformation aus der dritten Form in die zweite Form umzuwandeln, und

eine erste Steuereinheit zum Befehlen der zweiten Umwandlungseinheit, die Operationszustandsinformation aus der zweiten Form in die dritte Form umzuwandeln, wenn das Quellenzielumfeld die Emulatormaschine ist und das Destinationszielumfeld die Zielmaschine ist, daraufhin Befehlen der dritten Umwandlungseinheit, die Operationszustandsinformation aus der dritten Form in die erste Form umzuwandeln.

5. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 4, die des Weiteren umfasst:

einen seriellen Übertragungsport zur Eingabe und Ausgabe der Operationszustandsinformation der ersten Form von und in einen Prozessor, der in der Zielmaschine enthalten ist, wobei der serielle Übertragungsport mit dem Prozessor über eine erste Leitung verbunden ist; und

einen Einrichtungstreiber zur Eingabe und Ausgabe der Operationszustandsinformation der zweiten Form in eine und aus einer schaltungsintegrierten Emulatoreinrichtung, die in der Emulatormaschine enthalten ist, wobei der Mittelstreiber mit der schaltungsintegrierten Emulatoreinrichtung über eine zweite Leitung verbunden ist.

6. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 5, in der die Operationszustandsinformation aus Informationen zusammengesetzt ist, die in einem Register und einem Speicher des Quellenzielumfelds gespeichert sind.

7. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 6, in der die Zielmaschine, die Emulatormaschine und die Simulatoreinrichtung auch Zielumfelder genannt werden, wobei die in dem Speicher gespeicherte Information eine der folgenden ist:

ein Unterbrechungspunkt, um dem Prozessor zu befehlen, den Betrieb anzuhalten;

eine Verfolgungsdate, die aus zumindest einer Adresse eines Befehls in dem Programm gebildet ist, das ausgeführt worden ist; und

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eine Unterbrechungseinstellinformation zur Erzeugung eines Unterbrechungssignals, wenn eine durch die Bedienperson eingestellte, gewisse Bedingung erfüllt ist.

8. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

Speicherverwaltungsmittel zur Verwaltung von Speichern und Registern der Zielmaschine, der Emulatormaschine und der Simulatoreinrichtung, in dem die Speicher und die Register in Speicher und Register, die wirksame Werte speichern, und in Speicher und Register gruppiert werden, die unwirksame Werte speichern, und

Wieder-Schreibmittel zur Umwandlung unwirksamer Werte, die in Operationszustandsinformation enthalten sind, in Vorgabewerte, indem auf das Speicherverwaltungsmittel verwiesen wird, wenn die Operationszustandsinformation durch das Lesemittel aus dem Quellenzielumfeld gelesen wird, wobei

das Umwandlungsmittel die Operationszustandsinformation in eine Form des Destinationszielumfelds umwandelt, nachdem das Wieder-Schreibmittel die unwirksamen Werte in Vorgabewerte umgewandelt hat.

9. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die ferner umfasst:

ein Unterbrechungspunkt-Einstellverwaltungsmittel zur Verwaltung von Bereichen der Speicher und der Register der Zielmaschine, der Emulatormaschine und der Simulatoreinrichtung, indem die Bereiche zu Bereichen gruppiert werden, für die ein Unterbrechungspunkt eingestellt werden kann, und in Bereiche, für die ein Unterbrechungspunkt nicht eingestellt werden kann;

ein Bestimmungsmittel zur Bestimmung, ob ein Unterbrechungspunkt in den Destinationszielumfeld eingestellt werden soll, indem auf das Unterbrechungspunkt-Einstellverwaltungsmittel verwiesen wird, nachdem das Umwandlungsmittel die Operationszustandsinformation in die Form des Destinationszielumfelds umgewandelt hat; und

ein Mitteilungsmittel zur Mitteilung an die Bedienperson, dass der Unterbrechungspunkt in dem Destinationszielumfeld nicht gesetzt werden soll, wenn das Bestimmungsmittel bestimmt, dass der Unterbrechungspunkt in dem

Destinationszielumfeld nicht gesetzt werden soll.

10. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

ein Maximalwert-Speichermittel zum Speichern eines Werts, der die maximale Anzahl akkumulierter Adressen für jeweils die Zielmaschine, die Emulatormaschine und die Simulatoreinrichtung darstellt;

ein Adressenzahl-Erkennungsmittel zum Erkennen einer gegenwärtigen Anzahl von akkumulierten Adressen in dem Destinationszielumfeld; und

Mitteilungsmittel zur Mitteilung an die Bedienperson über einen Unterschied zwischen der gegenwärtigen Anzahl von akkumulierten Adressen und der maximalen Anzahl von akkumulierten Adressen.

11. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

ein Unterbrechungserzeugungs-Verwaltungsmittel zum Verwalten der Zielumfelder, indem die Zielumfelder in solche gruppiert werden, die eine Erfüllung einer Unterbrechungserzeugungsbedingung überwachen, und solche, die die Erfüllung der Unterbrechungserzeugungsbedingung nicht überwachen;

ein Bestimmungsmittel zur Bestimmung, ob das Destinationszielumfeld die Erfüllung der Unterbrechungserzeugungsbedingung überwacht, indem auf das Unterbrechungserzeugungs-Verwaltungsmittel verwiesen wird, nachdem das Umwandlungsmittel die Operationszustandsinformation in die Form des Destinationszielumfelds umgewandelt hat; und

ein Mitteilungsmittel zur Mitteilung an die Bedienperson, dass das Destinationszielumfeld die Erfüllung der Unterbrechungserzeugungsbedingung nicht überwacht, wenn das Bestimmungsmittel bestimmt, dass das Destinationszielumfeld die Erfüllung der Unterbrechungserzeugungsbedingung nicht überwacht.

12. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

ein erstes Interpretiermittel zum Interpretieren eines Befehls zum Überwachen einer Erzeugung eines Unterbrechungssignals, wenn das Befehlserfassungsmittel bestimmt, dass der

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gewisse Befehl nicht in dem von dem Empfangsmittel erhaltenen Kommando enthalten ist, wobei der Befehl in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde;

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ein zweites Interpretiermittel zum Interpretieren einer Kennungszahl eines Unterbrechungssignals und eines entsprechenden Destinationszielumfelds, wobei die Kennungszahl und das entsprechende Destinationszielumfeld in dem Kommando enthalten sind, das von der Empfangsmittel erhalten wird;

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ein Überwachungsmittel zum Überwachen der Erzeugung des Unterbrechungssignals in dem Quellenzielumfeld; und

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ein Bestimmungsmittel zur Bestimmung, wenn ein Unterbrechungssignal erzeugt ist, ob eine Kennungszahl des erzeugten Unterbrechungssignals zu der Kennungszahl passt, die durch das zweite Interpretiermittel interpretiert wurde, wobei

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das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wenn das Bestimmungsmittel bestimmt, dass die Kennungszahl des erzeugten Unterbrechungssignals zu der Kennungszahl passt, die durch das zweite Interpretiermittel interpretiert wurde.

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13. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

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ein erstes Interpretiermittel zum Interpretieren eines Befehls zum Überwachen eines Wiederschreibvorgangs von einem gewissen Speicher oder einem gewissen Register, wenn das Befehlserfassungsmittel bestimmt, dass der gewisse Befehl nicht in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wird, wobei der Befehl in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wird;

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ein zweites Interpretiermittel zum Interpretieren eines Befehls zum Ändern von einem gegenwärtigen Zielumfeld zu einem anderen Zielumfeld in dem Fall, dass der gewisse Speicher oder das gewisse Register wiedergeschrieben wurden, wobei der Befehl in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde; und

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ein Überwachungsmittel zum Überwachen des Wiederschreibens des gewissen Speichers

oder des gewissen Registers, wobei

das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wobei

das Umwandlungsmittel die Operationszustandsinformation in die Form des Destinationszielumfelds umwandelt, das das andere Zielumfeld ist, das das andere durch das zweite Interpretiermittel interpretierte Zielumfeld ist.

14. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die ferner umfasst:

ein erstes Interpretiermittel zum Interpretieren eines Befehls zum Ändern von Zielumfeldern, wenn das Befehlserfassungsmittel bestimmt, dass der gewisse Befehl nicht in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde, wobei der Befehl in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde;

ein zweites Interpretiermittel zum Interpretieren einer Tabelle, die die Beziehung zwischen einer Mehrzahl von Teilen des Programms und entsprechenden Zielumfeldern zeigt, wobei die Tabelle in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde;

ein drittes Interpretiermittel zum Interpretieren eines Befehls zum Überwachen einer Änderung des gegenwärtig ausgeführten Programmteils, wobei der Befehl in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde; und

ein Überwachungsmittel zum Überwachen der Änderung des gegenwärtig ausgeführten Programmteils in dem Quellenzielumfeld, wobei

das Spezifizierungsmittel umfasst:

eine Destinationsspezifizierungseinheit zum Spezifizieren eines Destinationszielumfelds, wenn das Überwachungsmittel die Änderung des gegenwärtig ausgeführten Teils erfasst, indem auf die Tabelle verwiesen wird, die durch das zweite Interpretiermittel interpretiert wird, wobei

das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wenn die Destinationsspezifizierungseinheit das Destinationszielumfeld spezifiziert.

15. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

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ein erstes Interpretiermittel zum Interpretieren eines Befehls zum Ändern von Zielumfeldern, wenn das Befehlserfassungsmittel bestimmt, das der gewisse Befehl nicht in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde, wobei der Befehl in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde;

ein zweites Interpretiermittel zum Interpretieren einer Tabelle, die die Beziehung zwischen einer Mehrzahl von variablen Werten, einer Mehrzahl von Werten, die in einem Speicher oder Register gespeichert werden können, und entsprechenden Zielumfeldern zeigt, wobei die Tabelle in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde;

ein drittes Interpretiermittel zum Interpretieren eines Befehls zum Überwachen einer Änderung einer gewissen Variablen des Programms, wobei der Befehl in dem Kommando enthalten ist, das von dem Empfangsmittel erhalten wurde; und

ein Überwachungsmittel zum Überwachen der Änderung der gewissen Variablen des Programms in dem Quellenzielumfeld, wobei

das Spezifizierungsmittel umfasst:

eine Destinationsspezifizierungseinheit zum Spezifizieren eines Destinationszielumfelds, wenn das Überwachungsmittel die Änderung der gewissen Variablen erfasst, indem auf die Tabelle verwiesen wird, die durch das zweite Interpretiermittel interpretiert wird, wobei

das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wenn die Destinationsspezifizierungseinheit das Destinationszielumfeld spezifiziert.

16. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

ein erstes Interpretiermittel zum Interpretieren einer Tabelle, die eine Beziehung zwischen einer Mehrzahl von Parametern, einer Mehrzahl von Teilen des Programms und entsprechenden Zielumfeldern zeigt, wenn das Befehlserfassungsmittel bestimmt, dass der gewisse Befehl nicht in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde, wobei die Tabelle in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde;

ein zweites Interpretiermittel zum Interpretieren

ren eines Befehls zum Überwachen einer Änderung eines gewissen Parameters des Programms, wobei der Befehl in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde; und

ein Überwachungsmittel zum Überwachen der Änderung des gewissen Parameters des Programms in dem Quellenzielumfeld, wobei

das Spezifizierungsmittel umfasst:

eine Destinationsspezifizierungseinheit zur Spezifizierung eines Destinationszielumfelds, wenn das Überwachungsmittel die Änderung des gewissen Parameters durch Verweis auf die Tabelle erfasst, die durch das erste Interpretiermittel interpretiert wird, wobei

das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wenn die Destinationsspezifizierungseinheit das Destinationszielumfeld spezifiziert.

17. Vorrichtung zur Programmfehlerbeseitigung nach Anspruch 7, die des Weiteren umfasst:

ein erstes Interpretiermittel zum Interpretieren einer Tabelle, die eine Beziehung zwischen einer Mehrzahl von Zielumfeldern und entsprechend geplanten Ausführungszeiten zeigt, wenn das Befehlserfassungsmittel bestimmt, dass der gewisse Befehl nicht in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wird, wobei die Tabelle in dem Kommando enthalten ist, das von der Empfangsmittel erhalten wurde; und ein Zeitmessmittel zum Messen einer gegenwärtigen Zeit, wobei das Spezifizierungsmittel umfasst:

eine Destinationsspezifizierungseinheit zum Spezifizieren eines Destinationszielumfelds, wenn die gegenwärtige Zeit zu einer der geplanten Ausführungszeiten passt, indem auf die Tabelle verwiesen wird, die durch das erste Interpretiermittel interpretiert wird; und

das Lesemittel die Operationszustandsinformation von dem Quellenzielumfeld liest, wenn die Destinationsspezifizierungseinheit das Destinationszielumfeld spezifiziert.

Revendications

1. Dispositif de débogage destiné à vérifier un programme devant être intégré dans une machine cible (30), en exécutant le programme dans l'un quelconque de la machine cible (30) elle-même, d'une machine d'émulation (20) émulant la machine cible

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(30) et d'un simulateur (1) simulant la machine (30) en termes de logiciel, dans lequel

chacun de la machine cible (30), de la machine d'émulation (20) et du simulateur (1) comprend des informations d'état de fonctionnement qui indiquent un état de fonctionnement du programme et fournissent en entrées et en sorties les informations d'état de fonctionnement sous une forme unique à chacun de la machine cible (30), de la machine d'émulation (20) et du simulateur (1), le dispositif de débogage comprenant:

un module de mémorisation d'environnement cible destiné à mémoriser des informations d'un environnement cible qui sont un nom d'identification de l'un quelconque de la machine cible (30), de la machine d'émulation (20) et du simulateur (1) en tant que cible d'environnement,

un moyen de réception destiné à recevoir une commande saisie par un opérateur,

un moyen de détection d'instruction destiné à évaluer si une certaine instruction est incluse dans la commande reçue par le moyen de réception,

un moyen de spécification destiné à spécifier, lorsque le moyen de détection d'instruction détermine que la certaine instruction est incluse dans la commande, un environnement cible spécifié par le nom d'identification mémorisé dans le module de mémorisation d'environnement cible en tant qu'environnement cible source et destiné à spécifier en tant qu'environnement cible de destination, l'un de la machine cible (30), de la machine d'émulation (20) et du simulateur (1), autre que le nom d'identification mémorisé dans le module de mémorisation d'environnement cible,

un moyen de lecture destiné à lire les informations d'état de fonctionnement à partir de l'environnement cible source,

un moyen de conversion destiné à convertir les informations d'état de fonctionnement lues par le moyen de lecture en des informations d'état de fonctionnement écrites sous une forme unique dans l'environnement cible de destination,

un moyen d'établissement destiné à établir les informations d'état de fonctionnement écrites sous la forme unique vers l'environnement cible de destination dans l'environnement cible de destination, et

un moyen de reprise de fonctionnement destiné à reprendre le fonctionnement du programme dans l'environnement cible de destination.

2. Dispositif de débogage selon la revendication 1, dans lequel

la machine cible fournit en entrées et en sor-

ties les informations d'état de fonctionnement sous une première forme, la machine d'émulation fournit en entrées et en sorties les informations d'état de fonctionnement sous une seconde forme et le simulateur fournit en entrées et en sorties les informations d'état de fonctionnement sous une troisième forme, dans lequel

le moyen de conversion comprend :

une première unité de conversion destinée à convertir les informations d'état de fonctionnement de la première à la troisième forme lorsque l'environnement cible source est la machine cible et que l'environnement cible de destination est le simulateur, et

une seconde unité de conversion destinée à convertir les informations d'état de fonctionnement de la seconde forme à la troisième forme lorsque l'environnement cible source est la machine d'émulation et que l'environnement cible de destination est le simulateur, dans lequel

le moyen d'établissement comprend :

une première unité d'établissement destinée à établir les informations d'état de fonctionnement dans le simulateur après que les informations d'état de fonctionnement aient été converties sous la troisième forme.

3. Dispositif de débogage selon la revendication 2, dans lequel

le moyen de conversion comprend :

une troisième unité de conversion destinée à convertir les informations d'état de fonctionnement de la troisième forme à la première forme lorsque l'environnement cible source est le simulateur et que l'environnement cible de destination est la machine cible, et

une quatrième unité de conversion destinée à convertir les informations d'état de fonctionnement de la troisième forme à la seconde forme lorsque l'environnement cible source est le simulateur et que l'environnement cible de destination est la machine d'émulation dans lequel

le moyen d'établissement comprend :

une seconde unité d'établissement destinée à établir les informations d'état de fonctionnement dans la machine cible après que les informations d'état de fonctionnement aient été converties sous la première forme, et

une troisième unité d'établissement destinée à établir les informations d'état de fonctionnement dans la machine d'émulation après que les informations d'état de fonctionnement aient été converties sous la seconde forme.

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4. Dispositif de débogage selon la revendication 3, dans lequel

le moyen de conversion comprend :

une première unité de commande destinée à 5
donner pour instruction à la première unité de
conversion de convertir les informations d'état
de fonctionnement de la première forme à la
troisième forme lorsque l'environnement cible 10
source est la machine cible et que l'environne-
ment cible de destination est la machine d'émul-
ation, puis à donner pour instruction à la qua-
atrième unité de conversion de convertir les in-
formations d'état de fonctionnement de la troi-
sième forme à la seconde forme, et
une seconde unité de commande destinée à
donner pour instruction à la seconde unité de
conversion de convertir les informations d'état
de fonctionnement de la seconde forme à la 20
troisième forme lorsque l'environnement cible
source est la machine d'émulation et que l'en-
vironnement cible de destination est la machine
cible, puis de donner pour instruction à la troi-
sième unité de conversion de convertir les in-
formations d'état de fonctionnement de la troi-
sième forme à la première forme. 25

5. Dispositif de débogage selon la revendication 4 comprenant en outre :

un port de transfert série destiné à fournir en 30
entrée à un processeur inclus dans la machine
cible, et en sortie depuis celui-ci, des informa-
tions d'état de fonctionnement de la première
forme, dans lequel le port de transfert série est 35
relié au processeur par l'intermédiaire d'une
première ligne, et
un pilote de dispositif destiné à fournir en en-
trée à un émulateur incorporé dans un circuit
inclus dans la machine d'émulation, et à fournir 40
en sortie à celui-ci, des informations d'état de
fonctionnement sous la seconde forme, dans
lequel le pilote de dispositif est relié à l'émula-
teur incorporé dans un circuit par l'intermédiaire
d'une seconde ligne. 45

6. Dispositif de débogage selon la revendication 5, dans lequel

les informations d'état de fonctionnement 50
sont composées d'informations mémorisées dans
un registre et dans une mémoire de l'environne-
ment cible source.

7. Dispositif de débogage selon la revendication 6, dans lequel

la machine cible, la machine d'émulation et le 55
simulateur sont également appelés environne-

ments cibles, dans lequel
les informations mémorisées dans la mémoire
représentent un élément parmi:
un point d'arrêt destiné à donner pour instruc-
tion au processeur d'arrêter son fonctionne-
ment,
des données de dépistage qui sont composées
d'au moins une adresse d'une instruction du
programme qui a été exécutée, et
des informations d'établissement d'interrup-
tion destinées à générer un signal d'interrup-
tion lorsqu'une certaine condition établie par l'opé-
rateur est satisfaite.

8. Dispositif de débogage selon la revendication 7 comprenant en outre :

un moyen de gestion de mémorisation destiné
à gérer des mémoires et des registres de la ma-
chine cible, de la machine d'émulation et du si-
mulateur en classant les mémoires et les regis-
tres en des mémoires et des registres mémori-
sant des valeurs effectives et des mémoires et
registres mémorisant des valeurs non effecti-
ves, et
un moyen de réécriture destiné à convertir des
valeurs non effectives incluses dans des infor-
mations d'état de fonctionnement en des va-
leurs par défaut en se référant au moyen de
gestion de mémorisation lorsque les informa-
tions d'état de fonctionnement sont lues à partir
de l'environnement cible source par le moyen
de lecture, dans lequel
le moyen de conversion convertit les informa-
tions d'état de fonctionnement sous une forme
de l'environnement cible de destination après
que le moyen de réécriture ait converti les va-
leurs non effectives en des valeurs par défaut.

9. Dispositif de débogage selon la revendication 7 comprenant en outre :

un moyen de gestion d'établissement de point
d'arrêt destiné à gérer des zones des mémoires
et des registres de la machine cible, de la ma-
chine d'émulation et du simulateur en classant
les zones en des zones pour lesquelles un point
d'arrêt peut être établi et des zones pour les-
quelles un point d'arrêt ne peut pas être établi,
un moyen de détermination destiné à détermi-
ner si un point d'arrêt doit être établi dans l'en-
vironnement cible de destination en se référant
au moyen de gestion d'établissement de point
d'arrêt après que le moyen de conversion ait
converti les informations d'état de fonctionne-
ment sous la forme de l'environnement cible de
destination, et
un moyen de notification destiné à notifier à

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l'opérateur que le point d'arrêt ne doit pas être établi dans l'environnement cible de destination lorsque le moyen de détermination détermine que le point d'arrêt ne doit pas être établi dans l'environnement cible de destination.

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10. Dispositif de débogage selon la revendication 7 comprenant en outre :

un module de mémorisation de valeur maximum destiné à mémoriser une valeur représentant le nombre maximum des adresses accumulées pour chacun de la machine cible, de la machine d'émulation et du simulateur, un moyen de reconnaissance de nombre d'adresses destiné à reconnaître un nombre en cours d'adresses accumulées dans l'environnement cible de destination, et un moyen de notification destiné à notifier à l'opérateur une différence entre le nombre en cours d'adresses accumulées et le nombre maximum d'adresses accumulées.

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11. Dispositif de débogage selon la revendication 7 comprenant en outre :

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un moyen de gestion de génération d'interruption destiné à gérer les environnements cibles en classant les environnements cibles en environnements qui surveillent la satisfaction d'une condition de génération d'interruption et en environnements qui ne surveillent pas la satisfaction de la condition de génération d'interruption, un moyen de détermination destiné à déterminer si l'environnement cible de destination surveille la satisfaction de la condition de génération d'interruption en se référant au moyen de gestion de génération d'interruption après que le moyen de conversion ait converti les informations d'état de fonctionnement sous la forme de l'environnement cible de destination, et un moyen de notification destiné à notifier à l'opérateur que l'environnement cible de destination ne surveille pas la satisfaction de la condition de génération d'interruption lorsque le moyen de détermination détermine que l'environnement cible de destination ne surveille pas la satisfaction de la condition de génération d'interruption.

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12. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une instruction de surveillance d'une génération d'un signal d'interruption lorsque le moyen de détection d'instruction détermine que la certaine instruction n'est pas incluse

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dans la commande reçue par le moyen de réception, l'instruction étant incluse dans la commande reçue par le moyen de réception, un second moyen d'interprétation destiné à interpréter un numéro d'identification d'un signal d'interruption et un environnement cible de destination correspondant, le numéro d'identification et l'environnement cible correspondant étant inclus dans la commande reçue par le moyen de réception, un moyen de surveillance destiné à surveiller la génération du signal d'interruption dans l'environnement cible source, et un moyen de détermination destiné à déterminer lorsqu'un signal d'interruption est généré, si un numéro d'identification du signal d'interruption généré correspond au numéro d'identification interprété par le second moyen d'interprétation, dans lequel le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source lorsque le moyen de détermination détermine que le numéro d'identification du signal d'interruption généré correspond au numéro d'identification interprété par le second moyen d'interprétation.

13. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une instruction de surveillance d'une réécriture de l'un d'une certaine mémoire et d'un certain registre lorsque le moyen de détection d'instruction détermine que la certaine instruction n'est pas incluse dans la commande reçue par le moyen de réception, l'instruction étant incluse dans la commande reçue par le moyen de réception, un second moyen d'interprétation destiné à interpréter une instruction de changement d'un environnement cible actuel en un autre environnement cible au cas où l'un de la certaine mémoire et du certain registre reçoit une réécriture, l'instruction étant incluse dans la commande reçue par le moyen de réception, et un moyen de surveillance destiné à surveiller la réécriture dans l'un de la certaine mémoire et du certain registre, dans lequel le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source, dans lequel le moyen de conversion convertit les informations d'état de fonctionnement sous la forme de l'environnement cible de destination qui est l'autre environnement cible interprété par le second moyen d'interprétation.

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14. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une instruction de modification des environnements cibles lorsque le moyen de détection d'instruction détermine que la certaine instruction n'est pas incluse dans la commande reçue par le moyen de réception, l'instruction étant incluse dans la commande reçue par le moyen de réception,

un second moyen d'interprétation destiné à interpréter une table qui indique la relation entre une pluralité de parties du programme et des environnements cibles correspondants, la table étant incluse dans la commande reçue par le moyen de réception,

un troisième moyen d'interprétation destiné à interpréter une instruction de surveillance d'une modification d'une partie en cours d'exécution du programme, l'instruction étant incluse dans la commande reçue par le moyen de réception, et

un moyen de surveillance destiné à surveiller la modification de la partie en cours d'exécution du programme dans l'environnement cible source, dans lequel

le moyen de spécification comprend :

une unité de spécification de destination destinée à spécifier un environnement cible de destination lorsque le moyen de surveillance détecte la modification de la partie en cours d'exécution en se référant à la table interprétée par le second moyen d'interprétation dans lequel le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source lorsque l'unité de spécification de destination spécifie l'environnement cible de destination.

15. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une instruction de modification des environnements cibles lorsque le moyen de détection d'instruction évalue que la certaine instruction n'est pas incluse dans la commande reçue par le moyen de réception, l'instruction étant incluse dans la commande reçue par le moyen de réception,

un second moyen d'interprétation destiné à interpréter une table qui montre la relation entre une pluralité de valeurs de variables, une pluralité de valeurs qui peuvent être mémorisées dans l'un d'une mémoire et d'un registre, et des

environnements cibles correspondants, la table étant incluse dans la commande reçue par le moyen de réception,

un troisième moyen d'interprétation destiné à interpréter une instruction de surveillance d'une modification d'une certaine variable du programme, l'instruction étant incluse dans la commande reçue par le moyen de réception, et un moyen de surveillance destiné à surveiller la modification de la certaine variable du programme dans l'environnement cible source, dans lequel

le moyen de spécification comprend :

une unité de spécification de destination destinée à spécifier un environnement cible de destination lorsque le moyen de surveillance détecte la modification de la certaine variable en se référant à la table interprétée par le second moyen d'interprétation dans lequel le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source lorsque l'unité de spécification de destination spécifie l'environnement cible de destination.

16. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une table qui montre la relation entre une pluralité de paramètres, une pluralité de parties du programme et des environnements cibles correspondants lorsque le moyen de détection d'instruction évalue que la certaine instruction n'est pas incluse dans la commande reçue par le moyen de réception, la table étant incluse dans la commande reçue par le moyen de réception,

un second moyen d'interprétation destiné à interpréter une instruction de surveillance d'une modification d'un certain paramètre du programme, l'instruction étant incluse dans la commande reçue par le moyen de réception, et un moyen de surveillance destiné à surveiller la modification du certain paramètre du programme dans l'environnement cible source, dans lequel

le moyen de spécification comprend :

une unité de spécification de destination destinée à spécifier un environnement cible de destination lorsque le moyen de surveillance détecte la modification du certain paramètre en se référant à la table interprétée par le premier moyen d'interprétation, dans lequel

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le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source lorsque l'unité de spécification de destination spécifie l'environnement cible de destination.

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17. Dispositif de débogage selon la revendication 7 comprenant en outre :

un premier moyen d'interprétation destiné à interpréter une table qui indique la relation entre une pluralité d'environnements cibles et les temps d'exécution prévus correspondants lorsque le moyen de détection d'instruction détermine que la certaine instruction n'est pas incluse dans le moyen reçu par le moyen de réception, la table étant incluse dans la commande reçue par le moyen de réception, et un moyen de mesure de temps destiné à mesurer un temps en cours, dans lequel

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le moyen de spécification comprend :

une unité de spécification de destination destinée à spécifier un environnement cible de destination lorsque le temps en cours correspond à l'un des temps d'exécution prévus en se référant à la table interprétée par le premier moyen d'interprétation, dans lequel le moyen de lecture lit les informations d'état de fonctionnement à partir de l'environnement cible source lorsque l'unité de spécification de destination spécifie l'environnement cible de destination.

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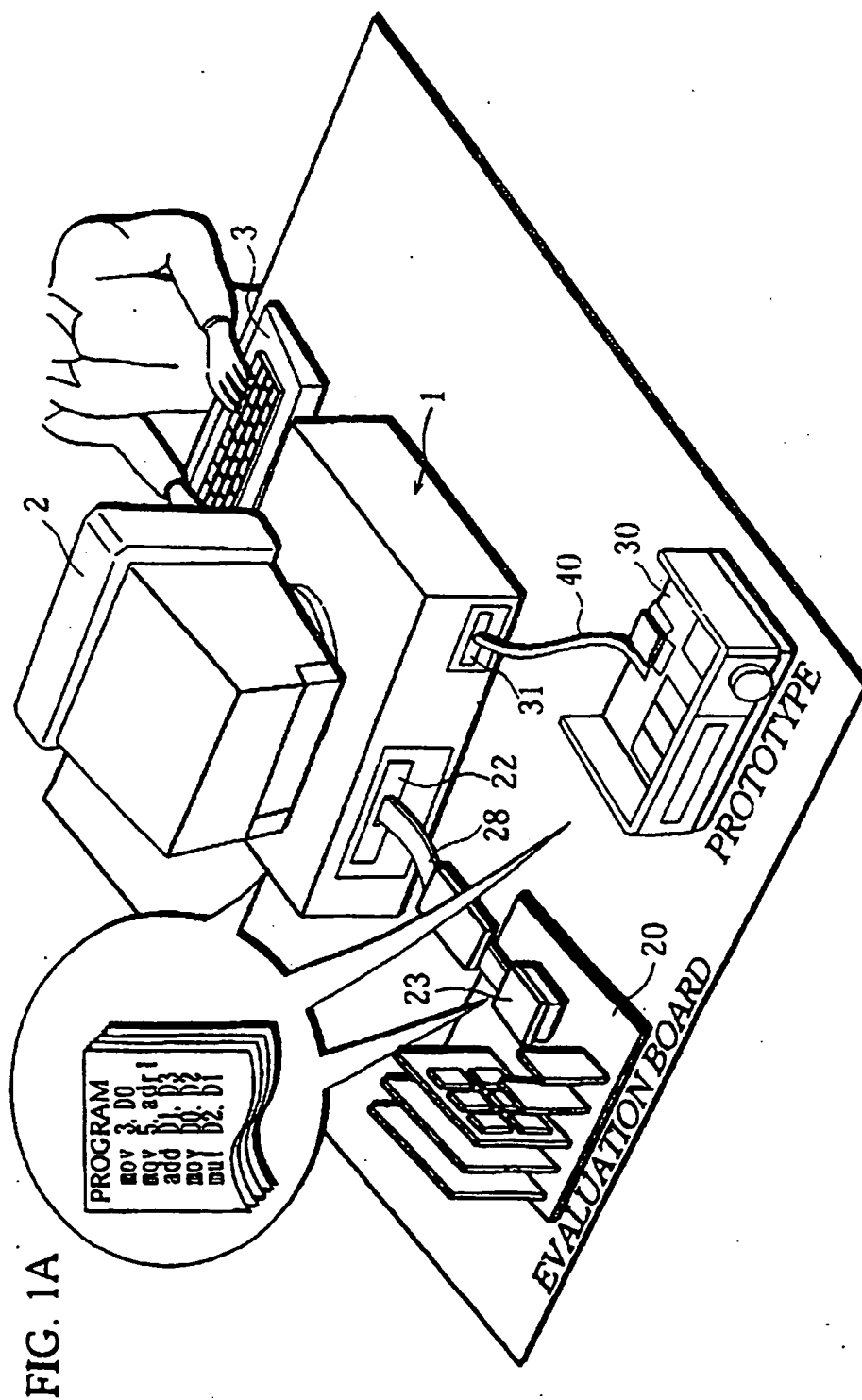
40

45

50

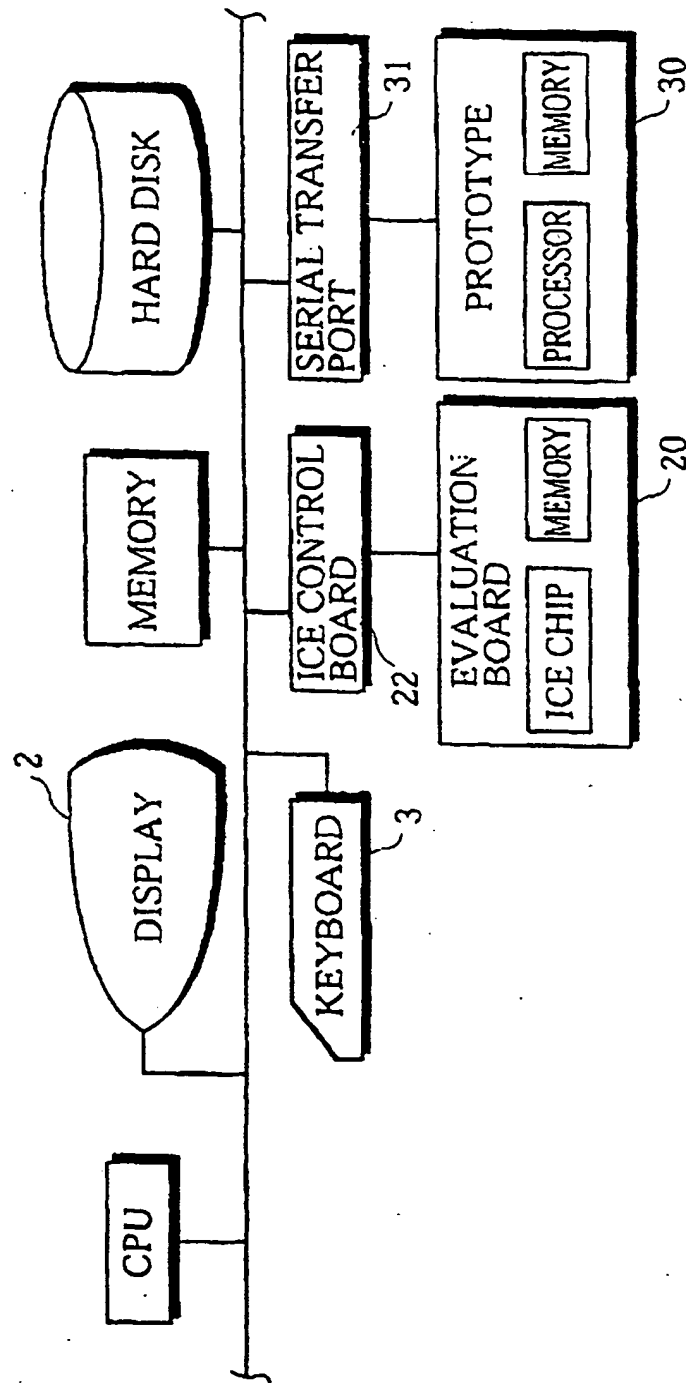
55

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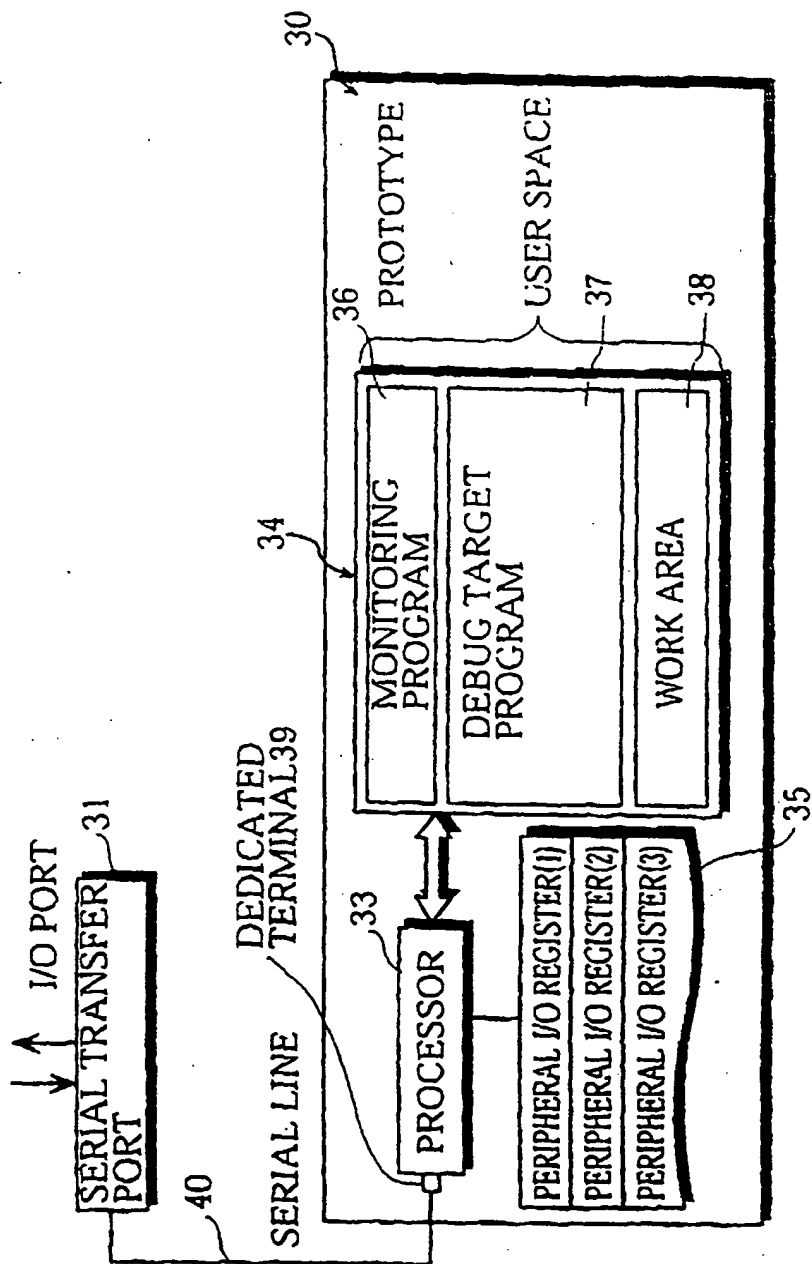
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FIG. 1B



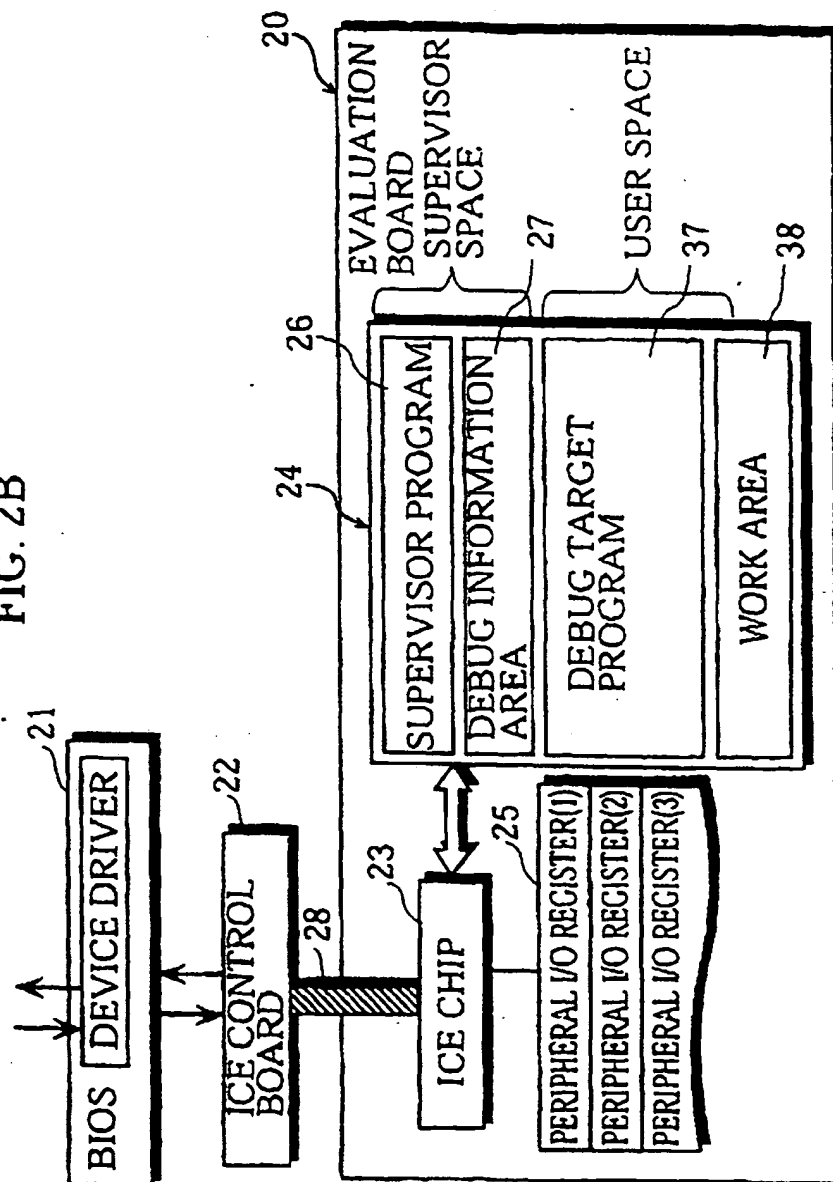
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FIG. 2A



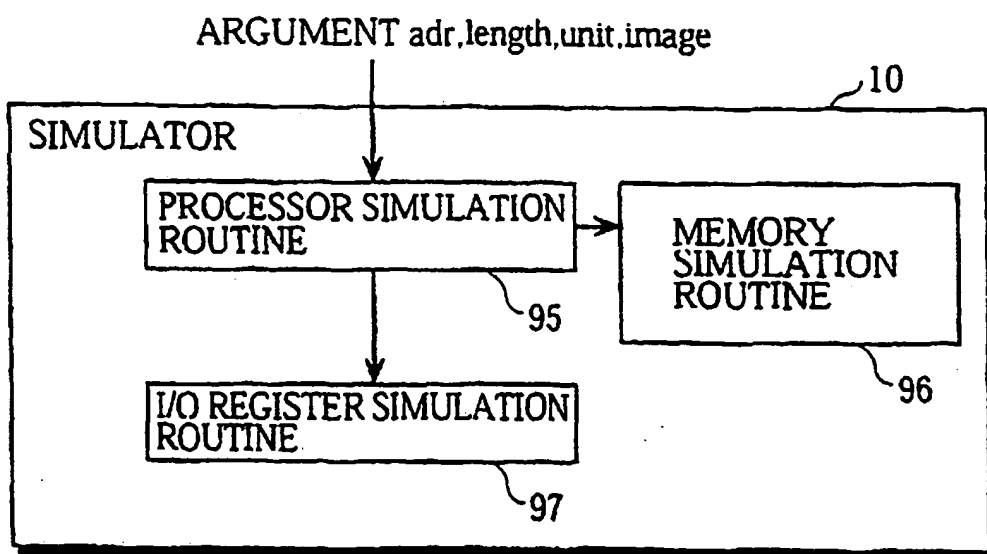
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FIG. 2B



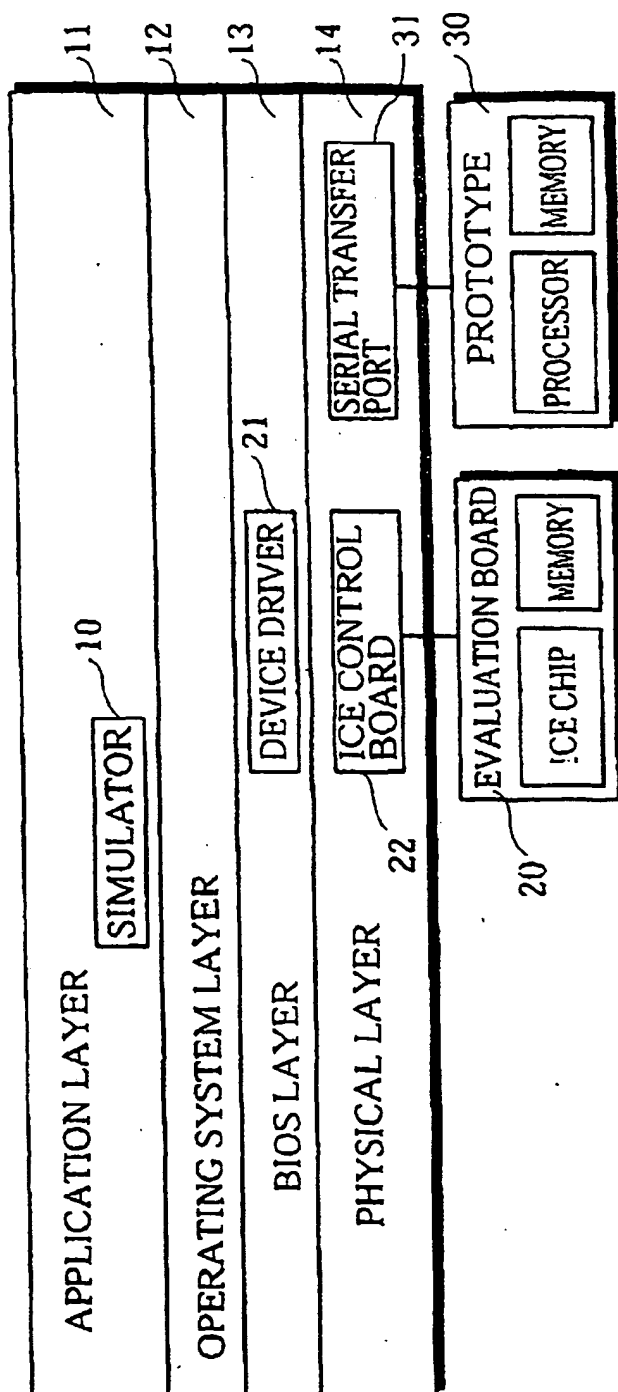
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FIG. 2C



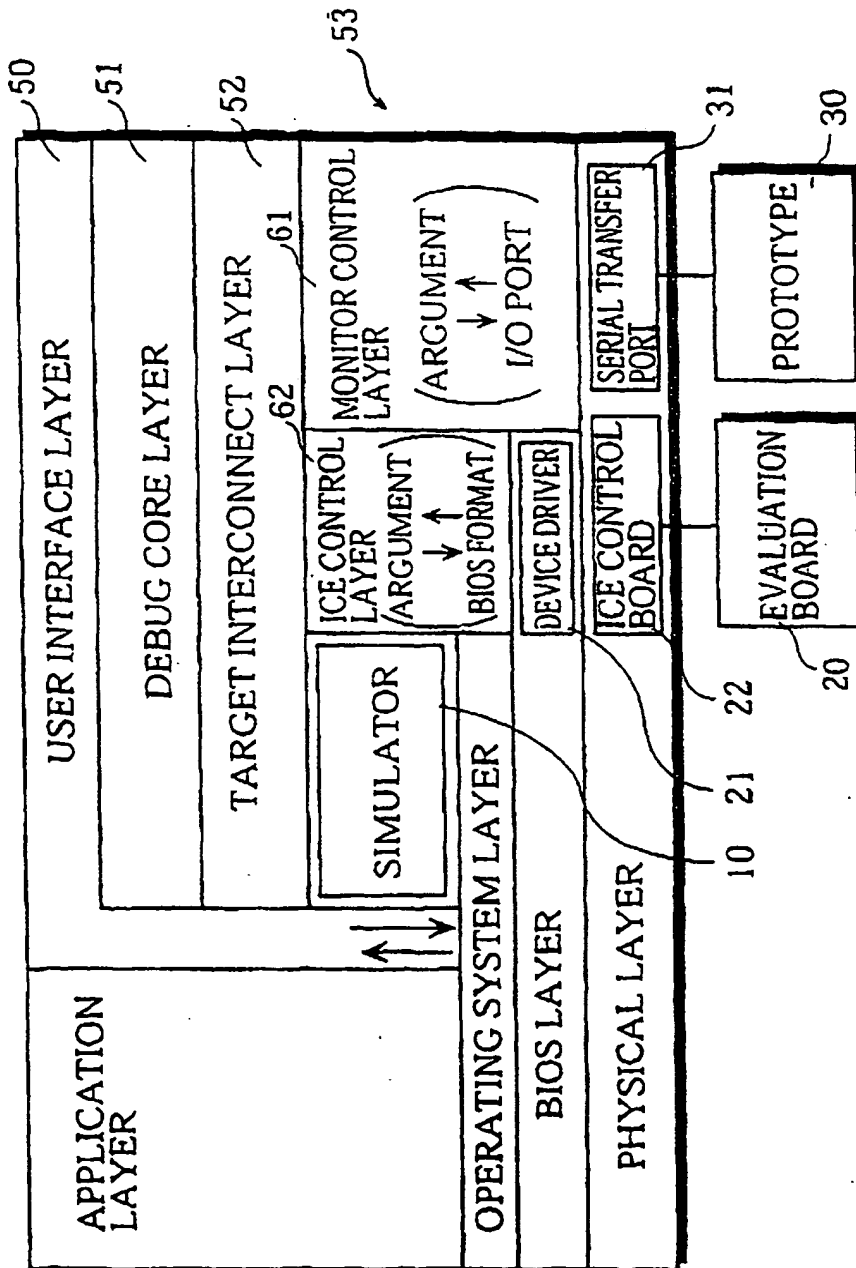
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FIG. 3

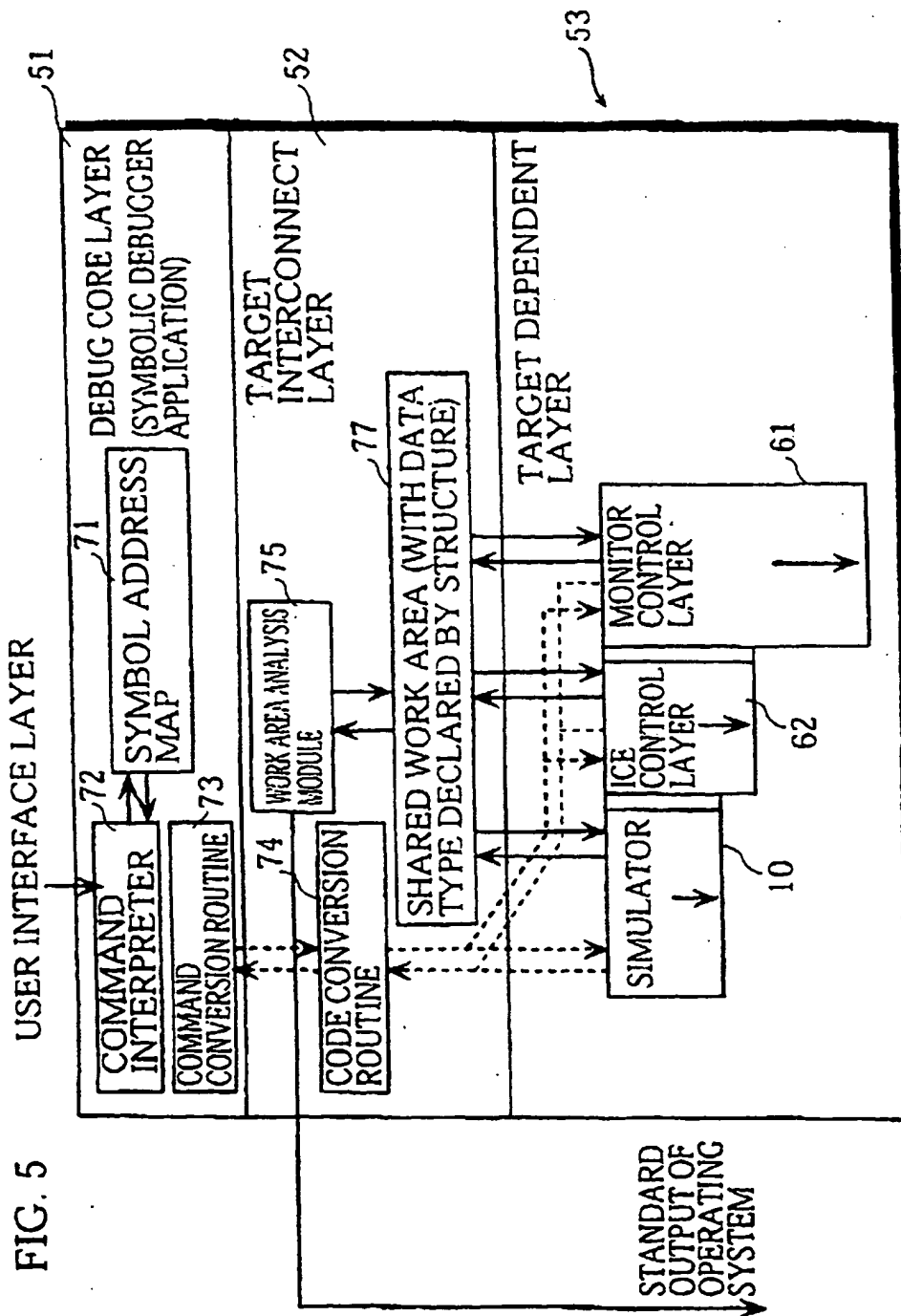


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FIG. 4



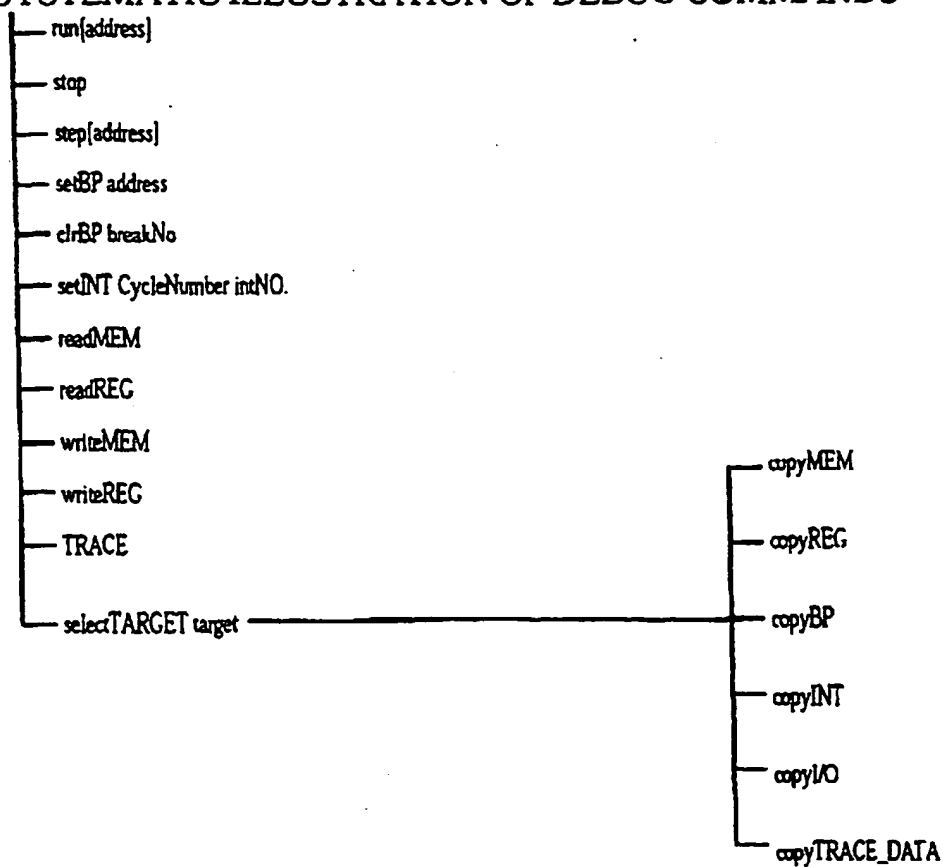
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FIG. 6A

SYSTEMATIC ILLUSTRATION OF DEBUG COMMANDS



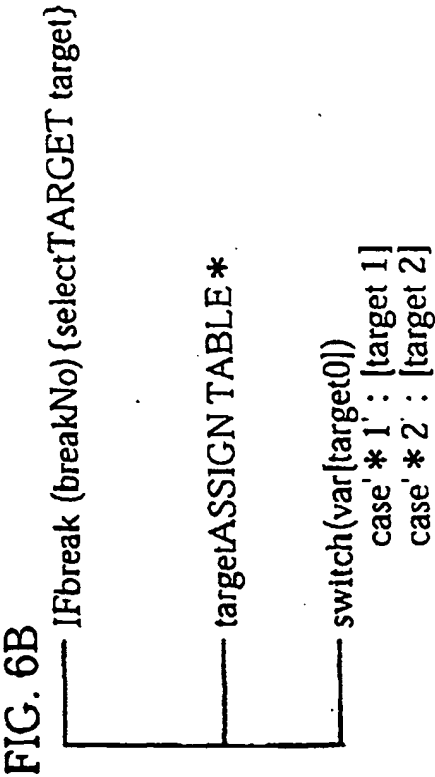


FIG. 6C

START ADDRESS 1	END ADDRESS 1	target 1
START ADDRESS 2	END ADDRESS 2	target 2
START ADDRESS 3	END ADDRESS 3	target 3
.	.	.
.	.	.
.	.	.
.	.	.
.	.	.
START ADDRESS n	END ADDRESS n	target n

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FIG. 7

* HARDWARE ENVIRONMENT IS SET TO TARGET1. ← P1
TARGET1 IS MONITOR TYPE.

* INPUT COMMAND
>readMEM 0x0100.16

* TARGET1 STORES FOLLOWING VALUE FOR 0x0100.16
FF FF FF FF FF FF FF FF FF FF FF FF FF FF

* INPUT COMMAND
>writeREG D1.03
* VALUE 03 WAS STORED IN D1 OF TARGET1

* INPUT COMMAND
>SetBP BP1,0x0123
* BREAKPOINT BP1 WAS SET AT 0x0123 OF TARGET1

* INPUT COMMAND
>RUN
* PROGRAM IS RUNNING UNDER TARGET1
* PROGRAM STOPPED AT 0x0123 OF TARGET1

* INPUT COMMAND
>SelectTARGET TARGET2

* HARDWARE ENVIRONMENT CHANGES FROM TARGET1
TO TARGET2
TARGET1 IS MONITOR TYPE
TARGET2 IS SIMULATOR TYPE

* WAIT UNTIL MEMORY DATA TRANSFER COMPLETES
* MEMORY DATA TRANSFER COMPLETED

* INPUT COMMAND
>

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FIG. 8

SUB-COMMAND (BEFORE CONVERSION)	HIGH FUNCTION CALL CODE (AFTER CONVERSION)
copyMEM	TCI_get_mem(adr.length,unit,image) TCI_set_mem(adr.length,unit,image)
copyReg	TCI_get_reg(regs,mask) TCI_set_reg(regs,mask)
copyBP	TCI_get_BP(adr.length,unit,image) TCI_set_BP(adr.length,unit,image)
copyINT	TCI_get_INT(cycle,intkind) TCI_set_INT(cycle,intkind)
copyI/O	TCI_get_I/O(adr.length,unit,image) TCI_set_I/O(adr.length,unit,image)
copyTRACE_DATA	TCI_get_TD(adr.length,unit,image) TCI_set_TD(adr.length,unit,image)

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FIG. 9

SOURCE TARGET HARDWARE ENVIRONMENT=MONITOR

DESTINATION TARGET HARDWARE ENVIRONMENT=SIMULATOR

HIGH FUNCTION CALL CODE

LOW FUNCTION CALL CODE

TCI_get_mem(adr,length,unit,image)→MON_get_mem(adr,length,unit,image)

TCI_set_mem(adr,length,unit,image)→SIM_set_mem(adr,length,unit,image)

TCI_get_reg(regs,mask)→MON_get_reg(regs,mask)

TCI_set_reg(regs,mask)→SIM_set_reg(regs,mask)

TCI_get_BP(adr,length,unit,image)→MON_get_BP(adr,length,unit,image)

TCI_set_BP(adr,length,unit,image)→SIM_set_BP(adr,length,unit,image)

TCI_get_INT(cycle,int,kind)→MON_get_INT(cycle,int,kind)

TCI_set_INT(cycle,int,kind)→SIM_set_INT(cycle,int,kind)

TCI_get_I/O(adr,length,unit,image)→MON_get_I/O(adr,length,unit,image)

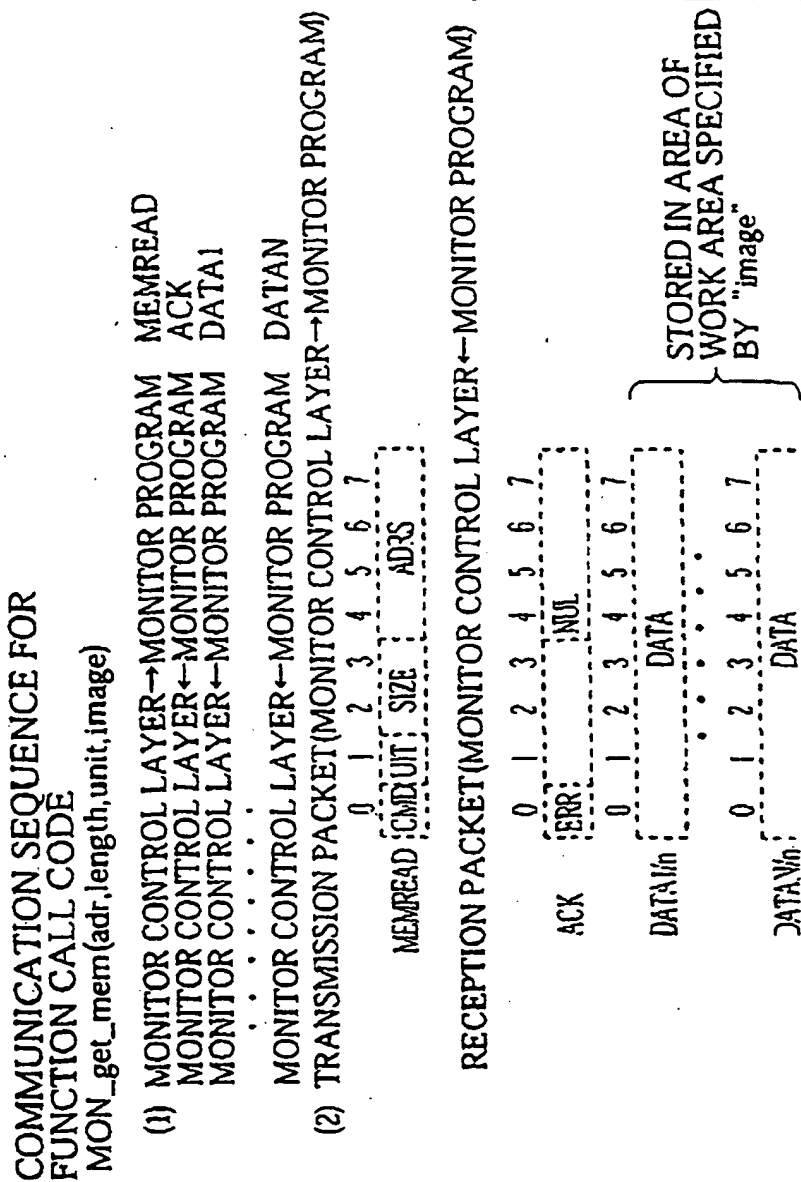
TCI_set_I/O(adr,length,unit,image)→SIM_set_I/O(adr,length,unit,image)

TCI_get_TD(adr,length,unit,image)→MON_get_TD(adr,length,unit,image)

TCI_set_TD(adr,length,unit,image)→SIM_set_TD(adr,length,unit,image)

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FIG. 10A



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FIG. 10B

COMMUNICATION SEQUENCE FOR
FUNCTION CALL CODE

MON_get_mem(addr, length, unit, image)

(1) MONITOR CONTROL LAYER → MONITOR PROGRAM MEMREAD
MONITOR CONTROL LAYER ← MONITOR PROGRAM ACK
MONITOR CONTROL LAYER ← MONITOR PROGRAM DATA1

MONITOR CONTROL LAYER ← MONITOR PROGRAM DATAN
MONITOR CONTROL LAYER ← MONITOR PROGRAM ACK2

(2) TRANSMISSION PACKET(MONITOR CONTROL LAYER → MONITOR PROGRAM)

MEMWRITE	CMD	UNIT	SIZE	ADDR
0	1	2	3	4
5	6	7		

DATA1
0
1
2
3
4
5
6
7

DATA2
0
1
2
3
4
5
6
7

DATA TO BE
TRANSFERRED
FROM AREA OF
WORK AREA
SPECIFIED BY "image"

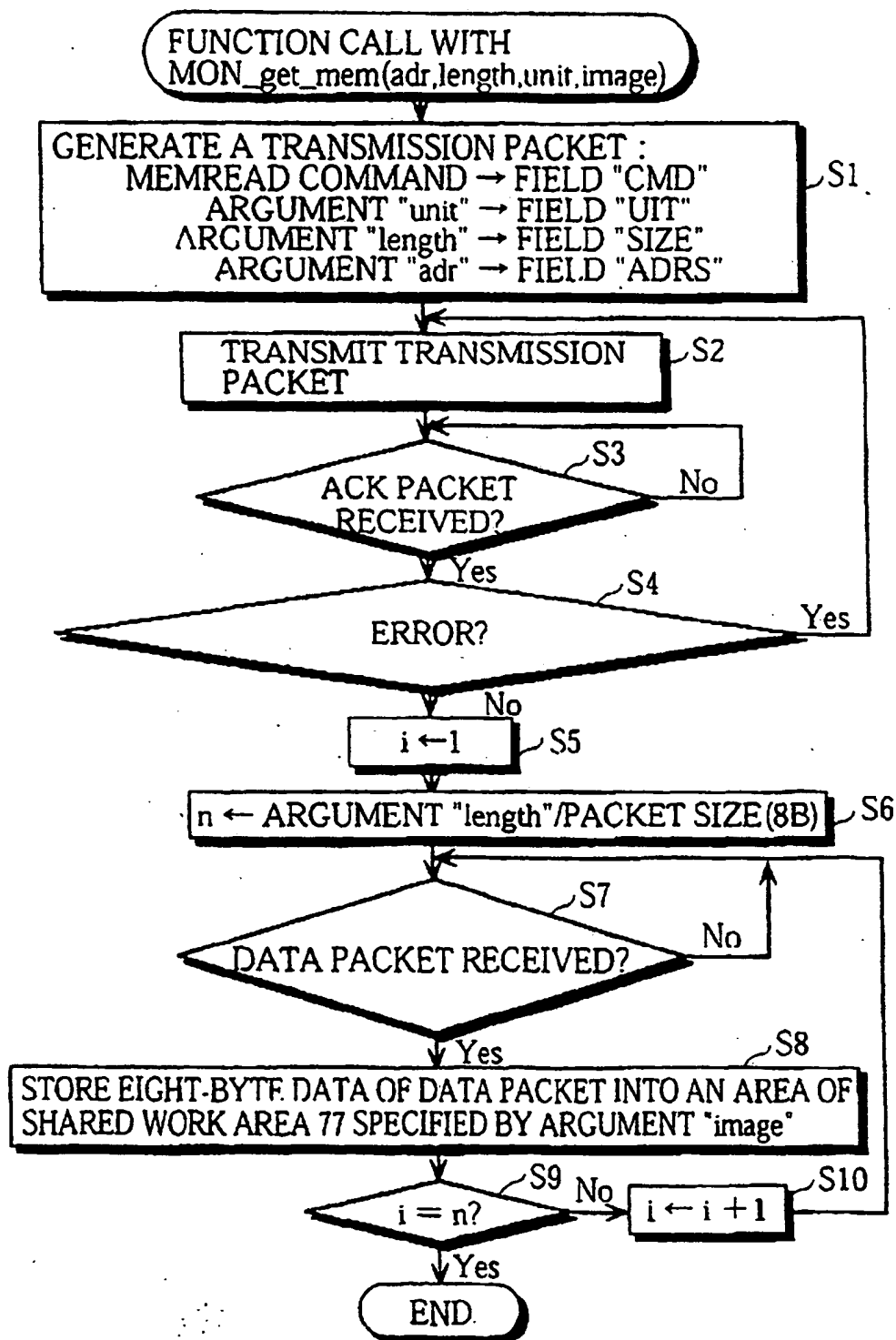
RECEPTION PACKET(MONITOR CONTROL LAYER ← MONITOR PROGRAM)

ACK1
0
1
2
3
4
5
6
7

ACK2
0
1
2
3
4
5
6
7

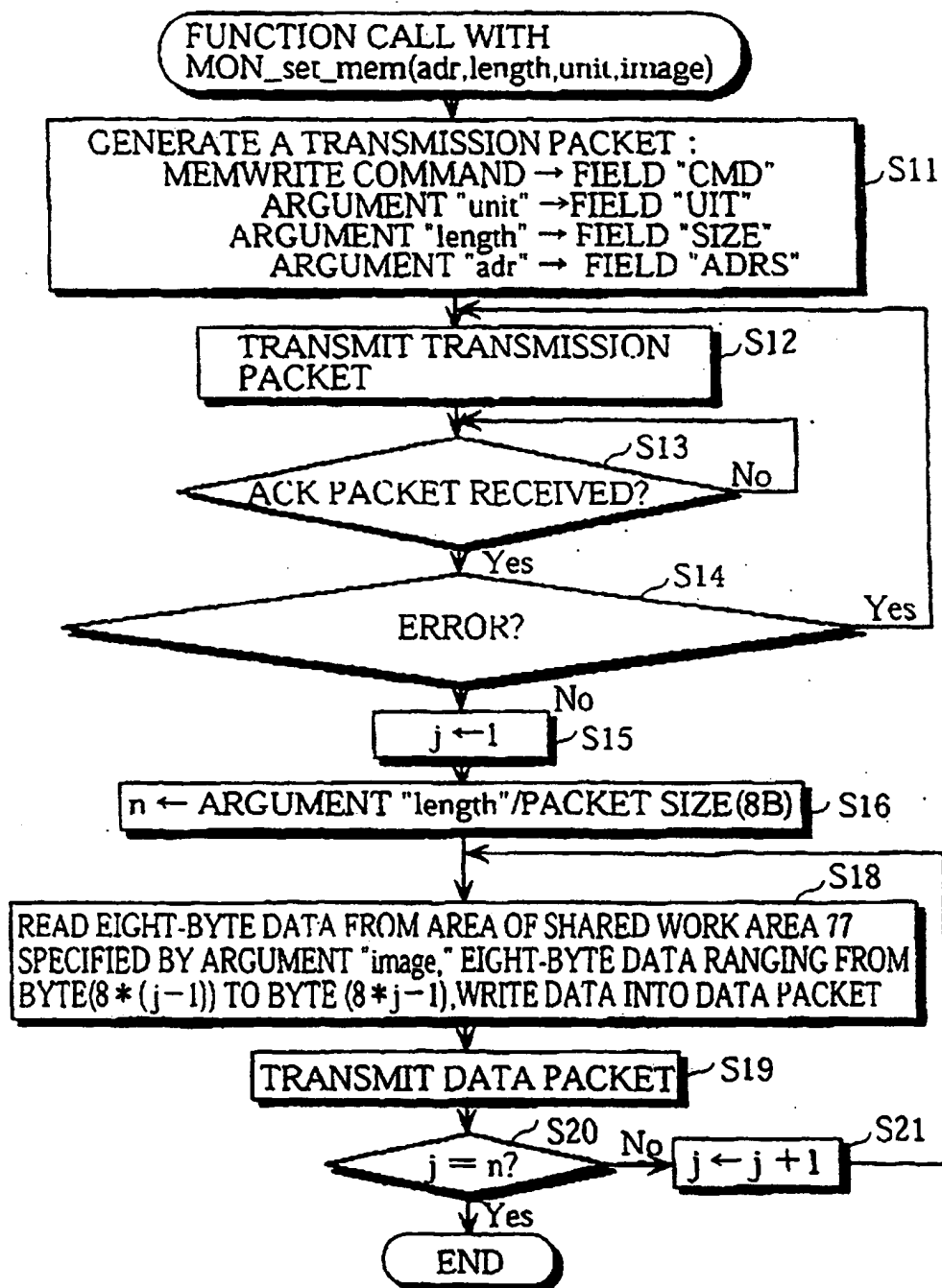
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FIG. 11A



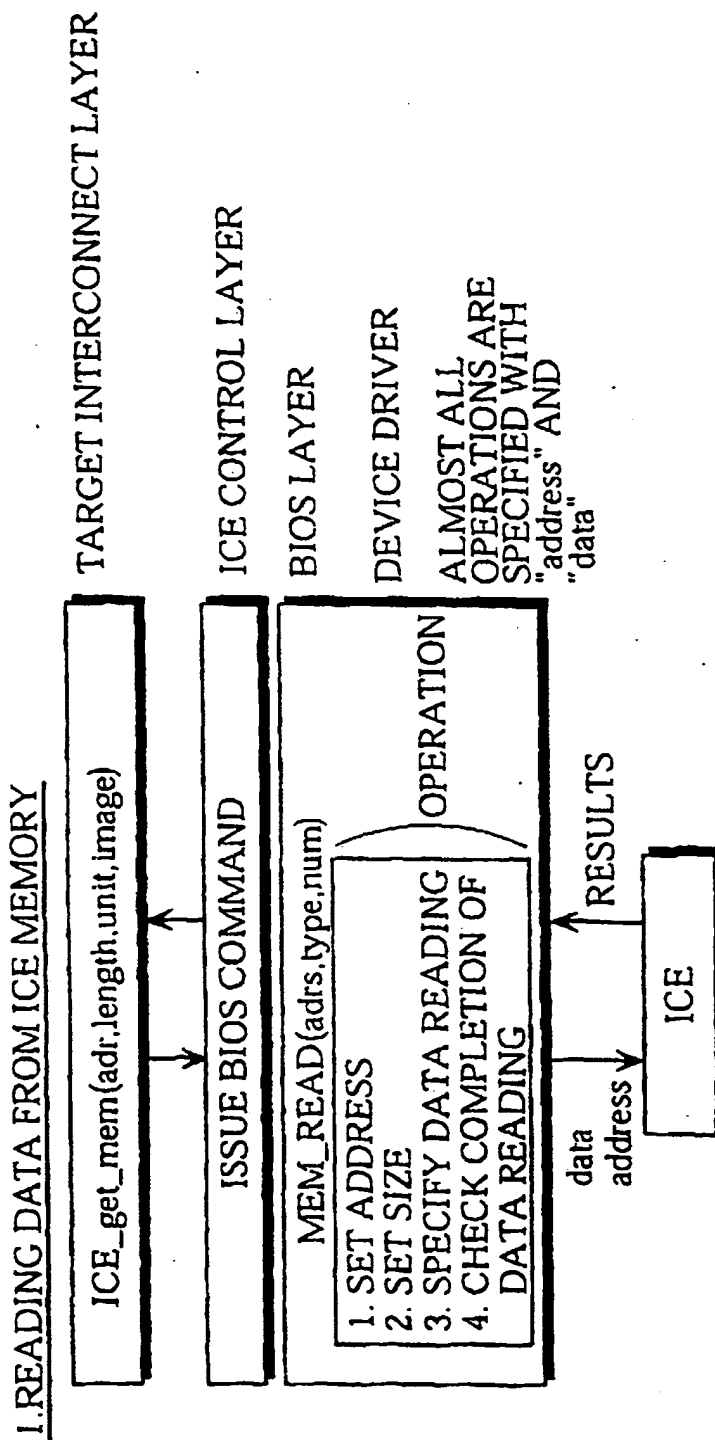
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FIG. 11B



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FIG. 12A



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FIG. 12B

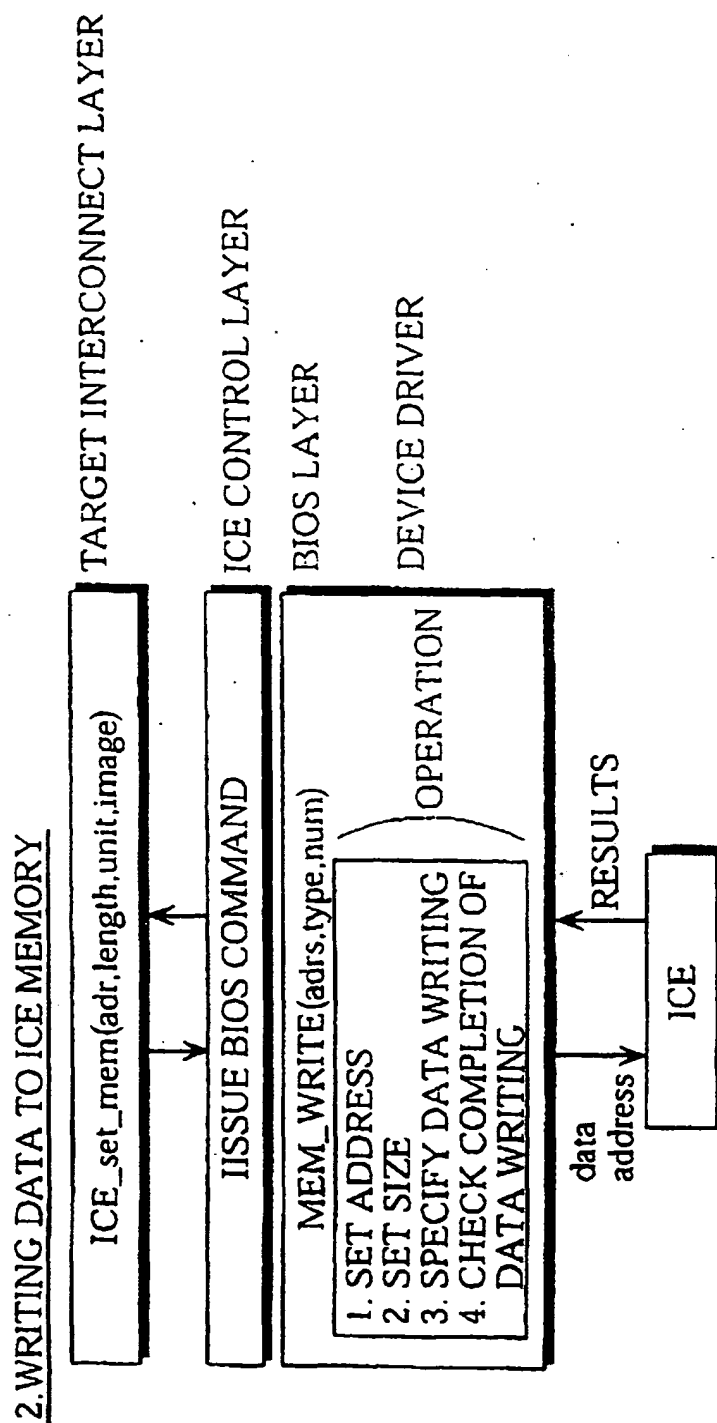


FIG. 13A

The diagram illustrates the architecture for FIG. 13A, showing the flow of data and control between various components. The components are organized into layers and functional blocks.

Target 1 : MONITOR
Target 2 : ICE
Target 3 : SIMULATOR

50 USER INTERFACE LAYER
SOURCE : TARGET 1
DESTINATION : TARGET 3

72 COMMAND INTERPRETER
copyMem, copyReg, copyINT, copyIO, copyTRACE_DATA

73 COMMAND CONVERSION ROUTINE
SRC :
TCL_set_mem(adrs, length, unit, image)
TCL_get_mem(adrs, length, unit, image)

74 CODE CONVERSION ROUTINE
DST :
SIM_set_mem(adrs, length, unit, image)
SRC : MON_get_mem(adrs, length, unit, image)

61 MONITOR CONTROL LAYER
STATE INFORMATION
T1
T2
MONITOR CONTROL
CONVERSION INTO MONITOR PROTOCOL
MEMREAD PACKET
DATA PACKET

21 RESULTS
data address
ICE

10 SIMULATOR
STATE INFORMATION
T2

62 ISSUE BIOS COMMAND
DEVICE DRIVER
MEM_READ(adrs, type, num)
OPERATION
1. SET ADDRESS
2. SET SIZE
3. SPECIFY DATA READING
4. CHECK COMPLETION OF DATA READING

DEBUG CORE LAYER 51

TARGET INTERCONNECT LAYER 52

51

Target 1 : MONITOR
Target 2 : ICE
Target 3 : SIMULATOR

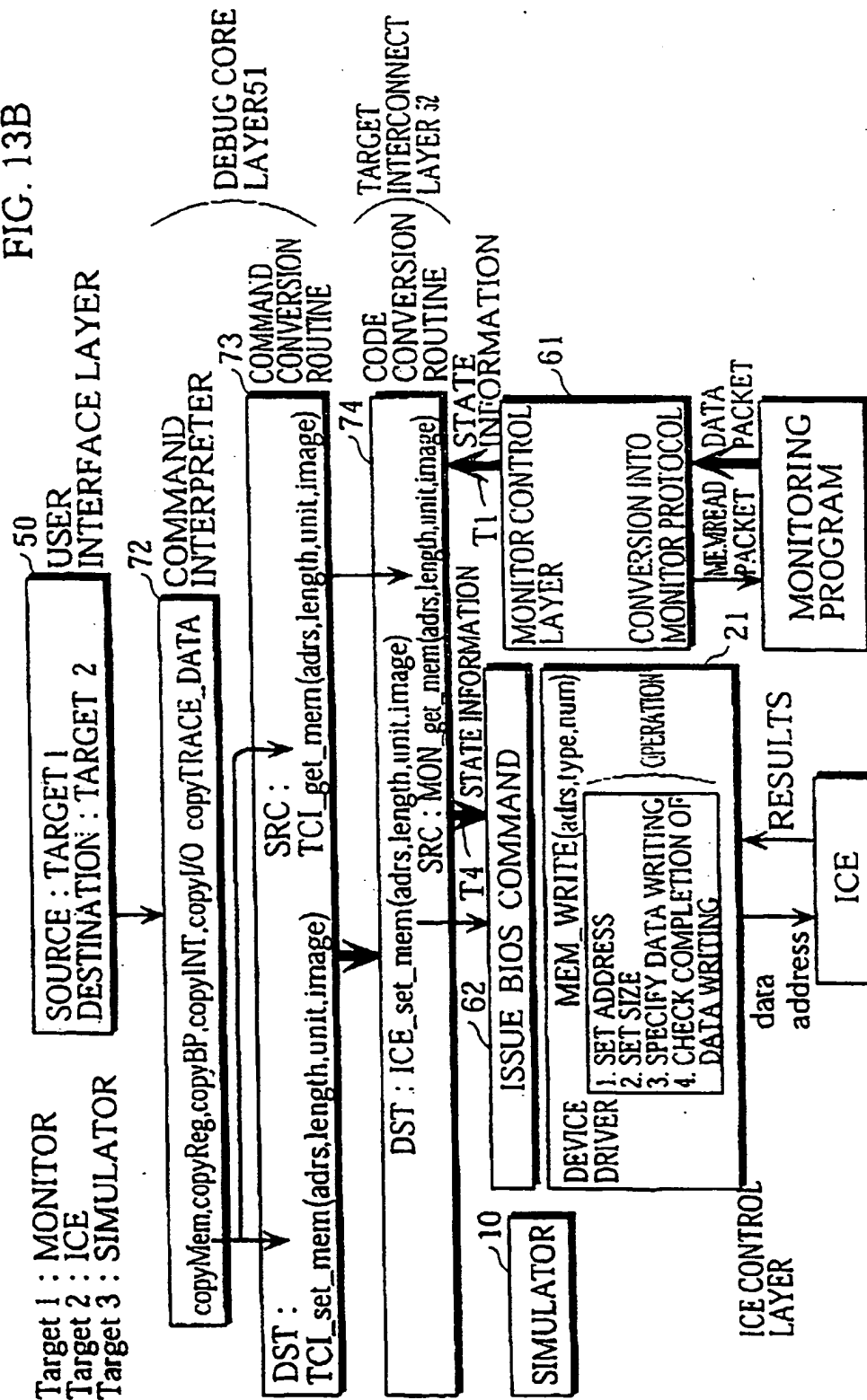


FIG. 13C

Target 1 : MONITOR
Target 2 : ICE
Target 3 : SIMULATOR

50 USER INTERFACE LAYER

72 COMMAND INTERPRETER

73 COMMAND CONVERSION ROUTINE

74 CODE CONVERSION ROUTINE

51 DEBUG CORE LAYER

52 TARGET INTERCONNECT LAYER

61 MONITOR CONTROL LAYER

21 CONVERSION INTO MONITOR PROTOCOL

MONITORING PROGRAM

10 SIMULATOR

ISSUE BIOS COMMAND

STATE INFORMATION 62

T5

T6

STATE INFORMATION

MEM_READ(adrs.type.num)

1. SET ADDRESS
2. SET SIZE
3. SPECIFY DATA READING
4. CHECK COMPLETION OF DATA READING

OPERATION

data address

RESULTS

ICE

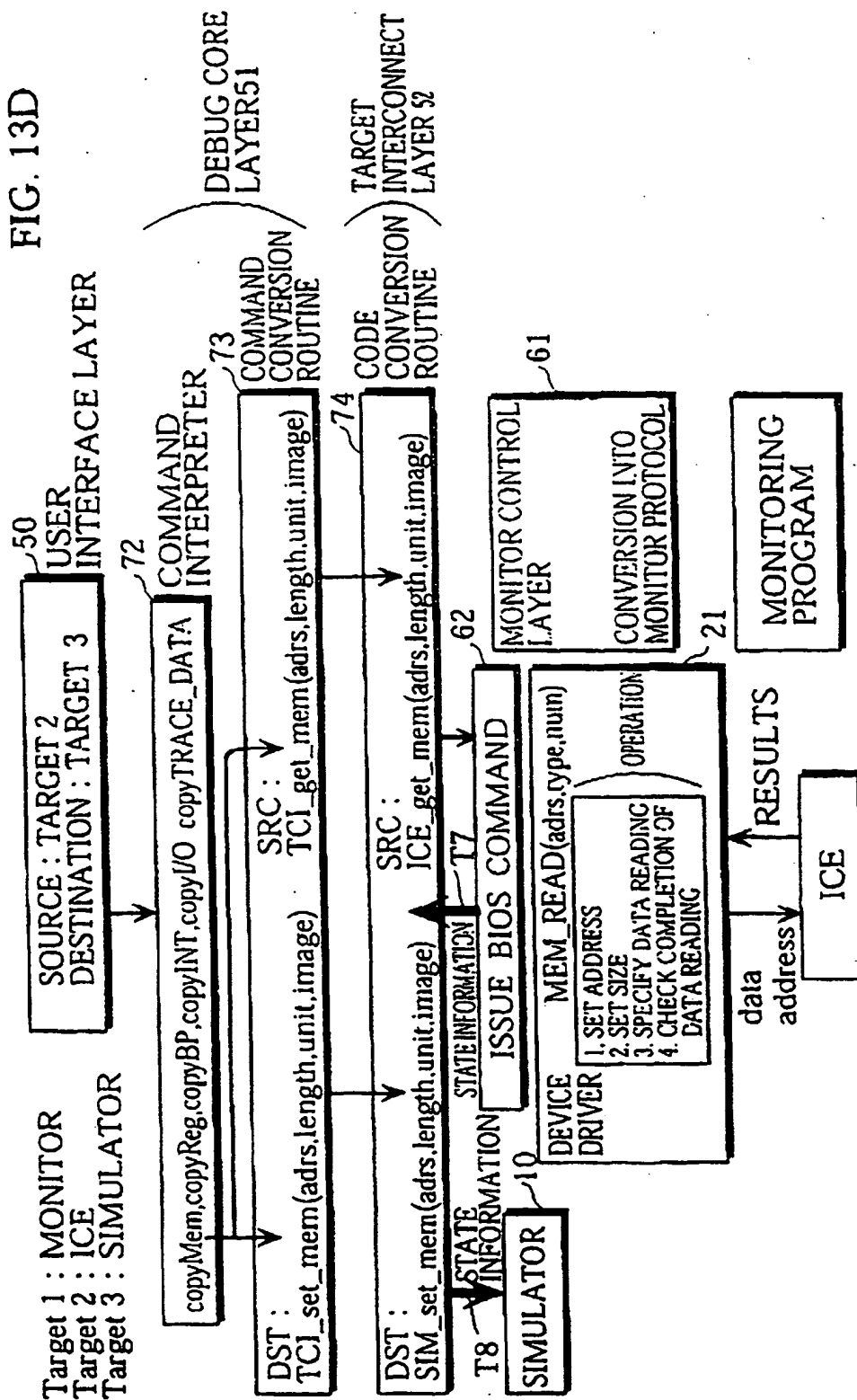
SRC : ICE_get_mem(adrs.length,unit,image)
TCL_get_mem(adrs.length,unit,image)
DST :
TCL_set_mem(adrs.length,unit,image)

SRC : MON_set_mem(adrs.length,unit,image)
DST : MON_get_mem(adrs.length,unit,image)

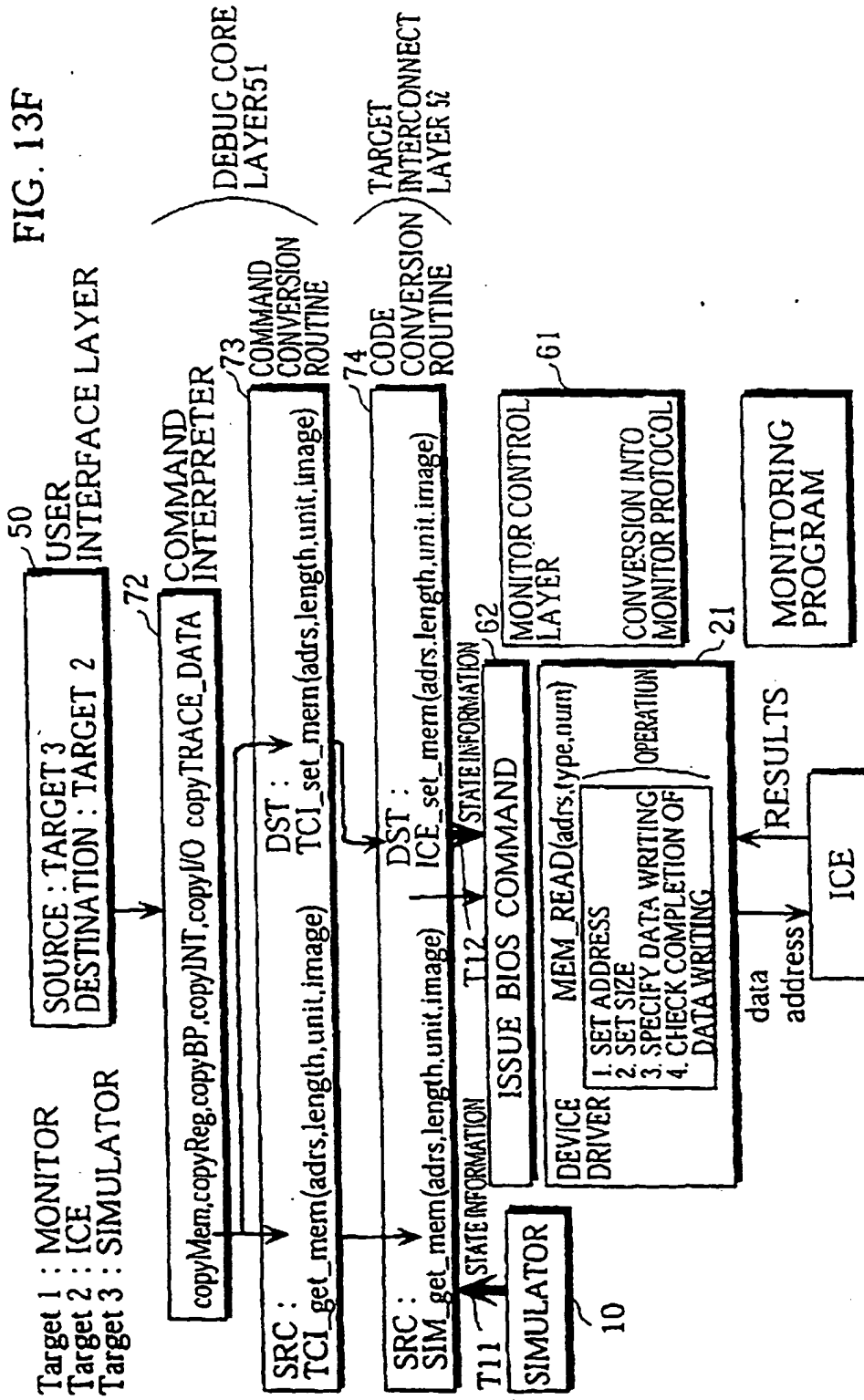
copyMem,copyReg,copyINT,copyIO,copyTRACE_DATA

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FIG. 13D



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FIG. 14A

/* BREAKPOINT ADDRESS */

```
BREAK_POINT[1] = 0x0020
BREAK_POINT[2] = 0x0250
BREAK_POINT[3] = 0x0300
BREAK_POINT[4] = 0x0350
BREAK_POINT[5] = 0x0510
BREAK_POINT[6] = 0x0530
```

FIG. 14B

/* INTERRUPT SIGNAL GENERATION CONDITION */

```
CONDITION[1] = 20cycle, Int3
CONDITION[2] = 150cycle, Int5
CONDITION[3] = 230cycle, Int6
CONDITION[4] = 250cycle, Int7
CONDITION[5] = 300cycle, Int8
```

FIG. 14C

/* TRACE DATA */

```
0x0000, 0x0001, 0x0002, 0x0003, 0x0004, 0x0005,
0x0006, 0x0007, 0x0008, 0x0009, 0x000A, 0x000B,
0x000C, 0x000D, 0x000E, 0x000F, 0x0010, 0x0011,
0x0012, 0x0013, 0x0014, 0x0015, 0x0016, 0x0017,
0x0018, 0x0019, 0x001A, 0x001B, 0x001C, 0x001D,
0x001E, 0x001F, 0x0020, 0x0021, 0x0022, 0x0023,
```

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FIG. 14D

target1	VALID_AREA1	START_ADDR1 ~ END_ADDR1
	VALID_AREA2	START_ADDR2 ~ END_ADDR2
	VALID_AREA3	START_ADDR3 ~ END_ADDR3
	VALID_AREA4	START_ADDR4 ~ END_ADDR4
target2	VALID_AREA1	START_ADDR1 ~ END_ADDR1
	VALID_AREA3	START_ADDR3 ~ END_ADDR3
	VALID_AREA5	START_ADDR5 ~ END_ADDR5
	VALID_AREA6	START_ADDR6 ~ END_ADDR6
target3	VALID_AREA2	START_ADDR2 ~ END_ADDR2
	VALID_AREA4	START_ADDR4 ~ END_ADDR4
	VALID_AREA5	START_ADDR5 ~ END_ADDR5
	VALID_AREA7	START_ADDR7 ~ END_ADDR7

FIG. 14E

target1	SPACE_FOR_TRACE_DATA	MAX 16Kbyte
target2	SPACE_FOR_TRACE_DATA	MAX 1Kbyte
target3	SPACE_FOR_TRACE_DATA	MAX 32Kbyte

FIG. 14F

target1	CYCLE_NUMBER_COUNT	INVALID
target2	CYCLE_NUMBER_COUNT	VALID
target3	CYCLE_NUMBER_COUNT	VALID

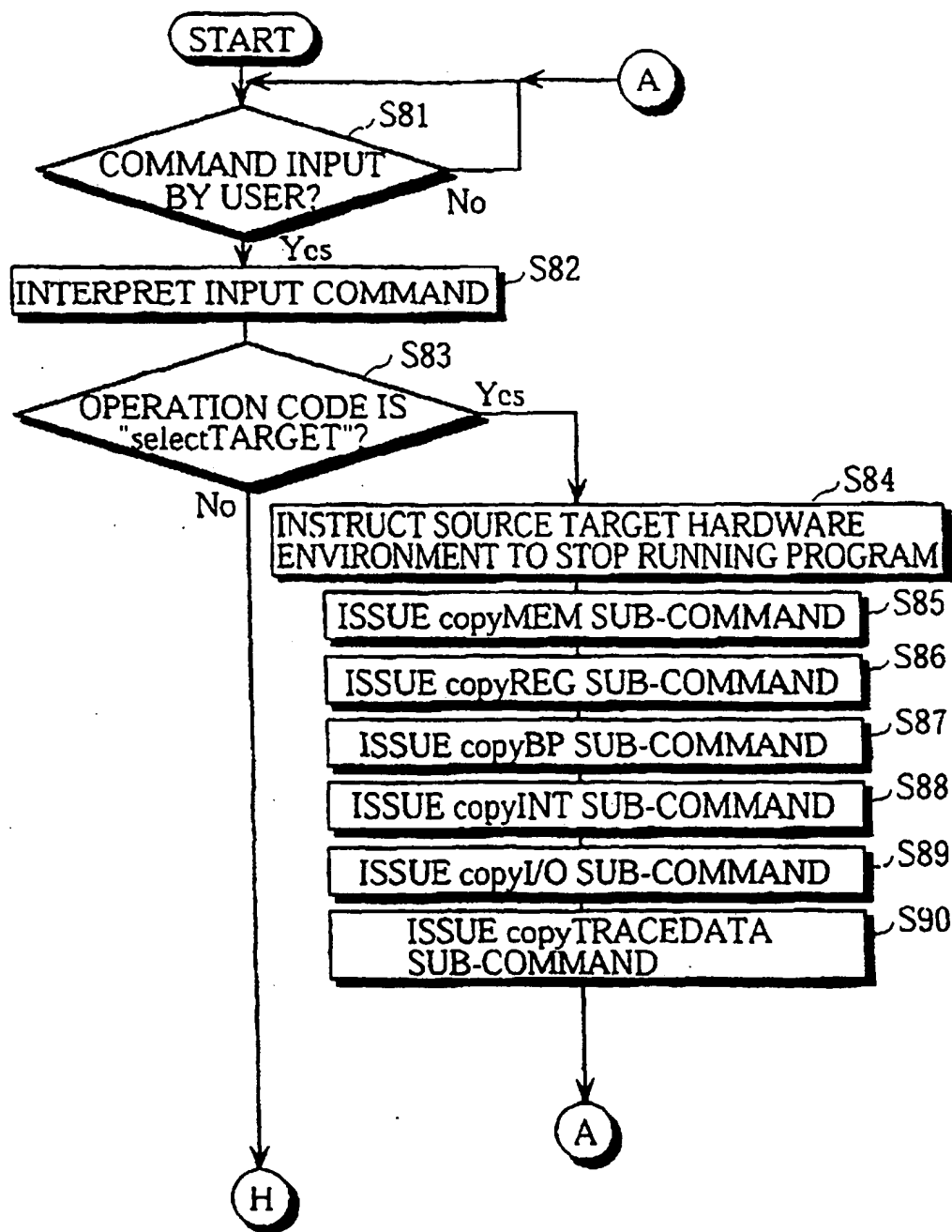
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FIG. 14G

target1		
I/O_REGISTER_ADDR1	PSW=STATUS1	0x1F
	PSW=STATUS2	0x2A
	PSW=STATUS3	0x3B
I/O_REGISTER_ADDR2	PSW=STATUS1	0x41
	PSW=STATUS2	0x51
	PSW=STATUS3	0x56
I/O_REGISTER_ADDR3	PSW=STATUS1	0x18
	PSW=STATUS2	0x22
	PSW=STATUS3	0x24
target2		
I/O_REGISTER_ADDR1	PSW=STATUS1	0x33
	PSW=STATUS2	0x32
	PSW=STATUS3	0x41
I/O_REGISTER_ADDR2	PSW=STATUS1	0x54
	PSW=STATUS2	0x56
	PSW=STATUS3	0x58
I/O_REGISTER_ADDR3	PSW=STATUS1	0xA1
	PSW=STATUS2	0x98
	PSW=STATUS3	0x75
target3		
I/O_REGISTER_ADDR1	PSW=STATUS1	0x18
	PSW=STATUS2	0x12
	PSW=STATUS3	0x33
I/O_REGISTER_ADDR2	PSW=STATUS1	0x42
	PSW=STATUS2	0x52
	PSW=STATUS3	0xB2
I/O_REGISTER_ADDR3	PSW=STATUS1	0x31
	PSW=STATUS2	0x54
	PSW=STATUS3	0x52

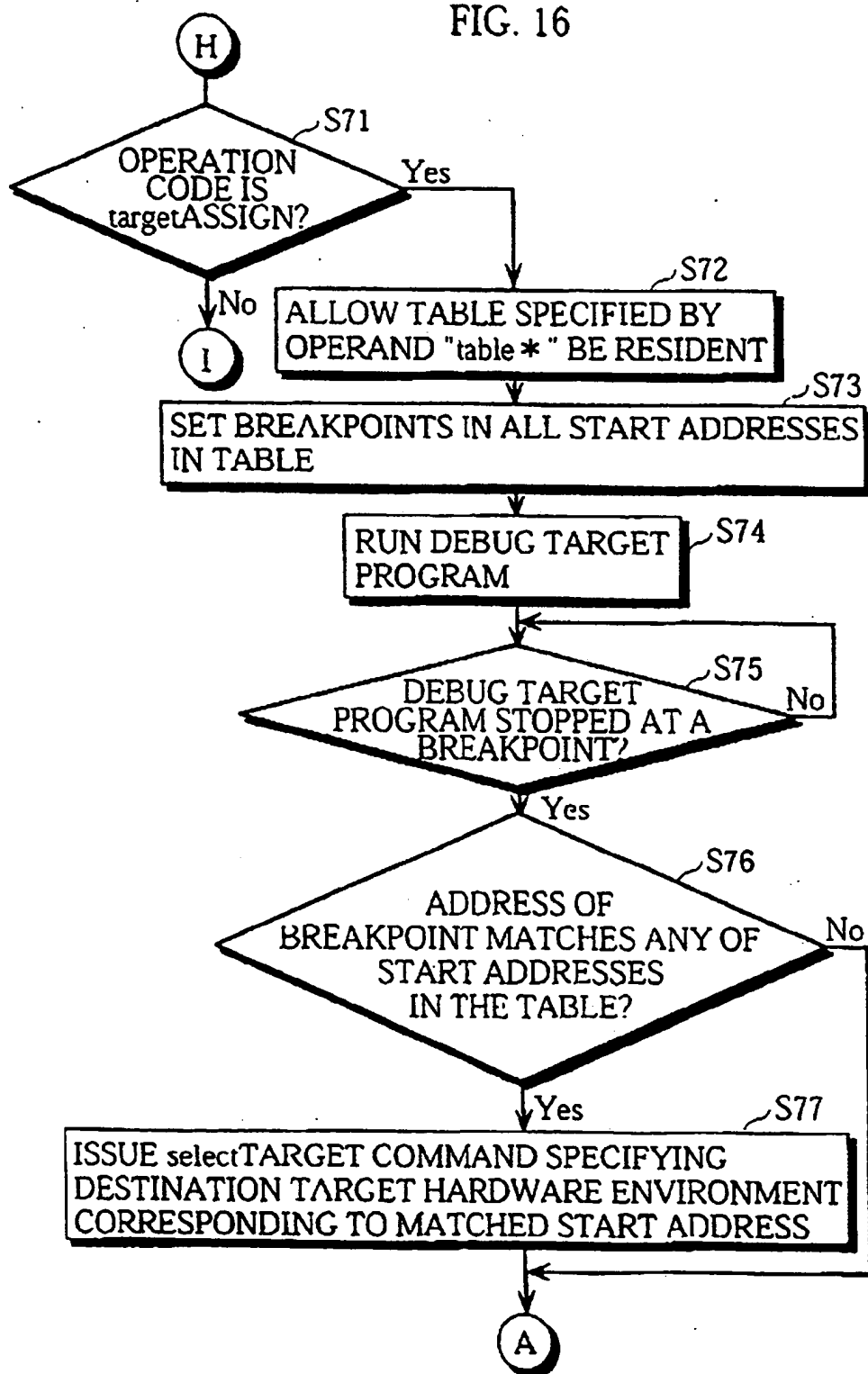
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FIG. 15



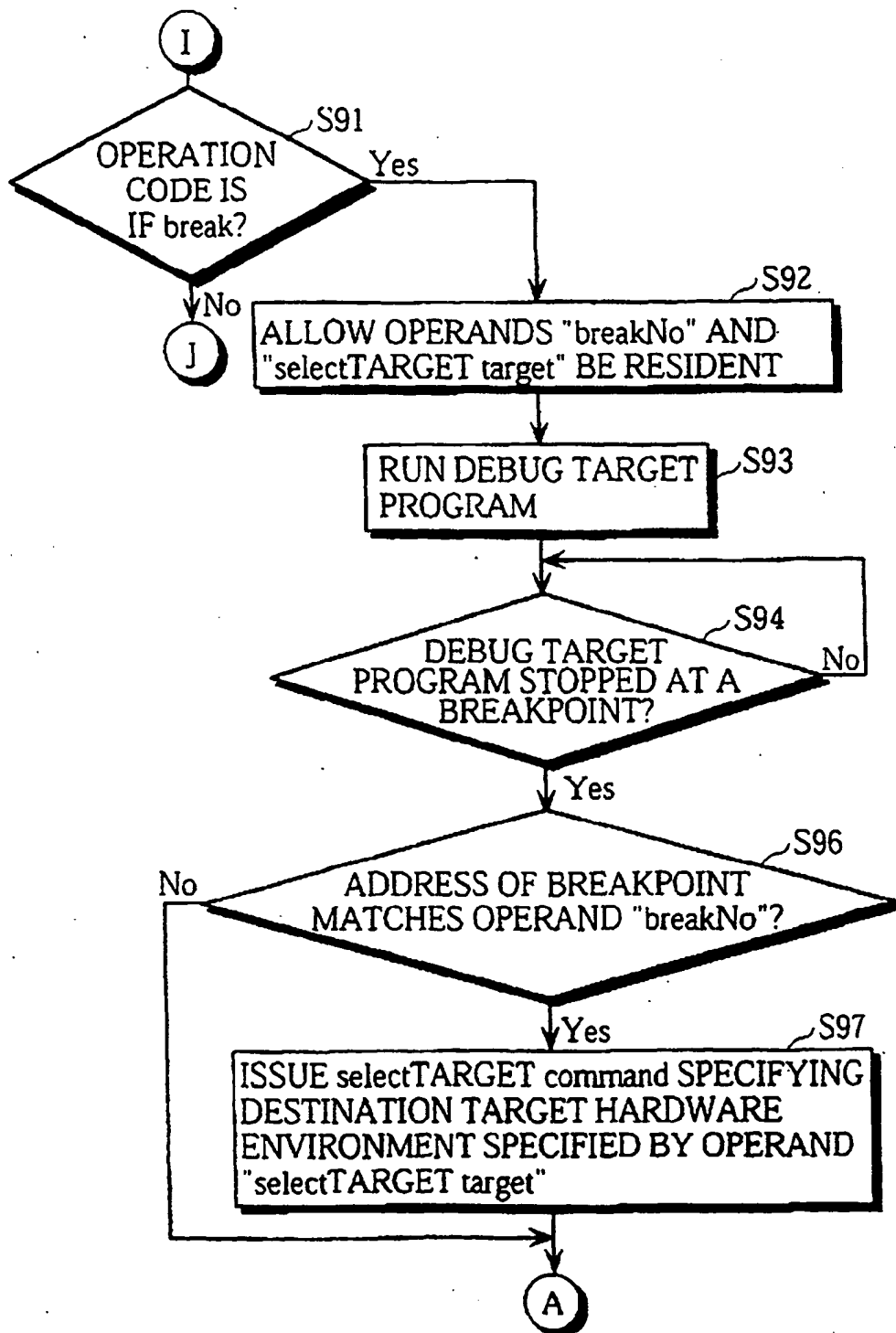
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FIG. 16



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FIG. 17



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FIG. 18

